



# Lattice computing for Artificial Intelligence applications

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# Contents

- Introductory ideas and history
- Review of early models
  - Fuzzy ART
  - Max-min classifiers
- Recent approaches
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- Conclusions and the future



# Introduction

- Lattice computing assumes that the basic computing structure is a lattice.
- A lattice  $(L, \vee, \wedge)$  is a Poset  $(L, \leq)$  any two of whose elements have
  - a supremum, denoted by  $x \vee y$
  - an infimum, denoted by  $x \wedge y$



# Introduction

- Poset

A *partially-ordered set*, briefly **poset**  $(\mathcal{P}, \leq)$ , is a set  $\mathcal{P}$  in which a binary relation  $\leq$  is defined that is a *partial ordering*, i.e., satisfies the following three properties for all  $X, Y, Z \in \mathcal{P}$ :

(P1).  $X \leq X$  (reflexive)

(P2).  $X \leq Y$  and  $Y \leq X$  imply  $X = Y$  (antisymmetric)

(P3).  $X \leq Y$  and  $Y \leq Z$  imply  $X \leq Z$  (transitive)



# Introduction

- Computational paradigm shift (Ritter)
  - Traditional Artificial Neural Networks are defined on the ring  $(\mathbb{R}, +, \times)$

$$\tau_j(\mathbf{x}) = \sum_{i=1} x_i w_{ij} - \theta_j$$

- Lattice ANN work on the semi-rings

$$(\mathbb{R}_{-\infty}, \vee, +) \text{ or } (\mathbb{R}_{\infty}, \wedge, +)$$

$$\tau_j(\mathbf{x}) = p_j \bigvee_{i=1}^n r_{ij}(x_i + w_{ij}) \quad \tau_j(\mathbf{x}) = p_j \bigwedge_{i=1}^n r_{ij}(x_i + w_{ij})$$



# Introduction

- Biological justification (Ritter)
  - Dendrites account for 50% of brain mass
  - Dendrite computation is more akin to AND, XOR, NOT logical operations

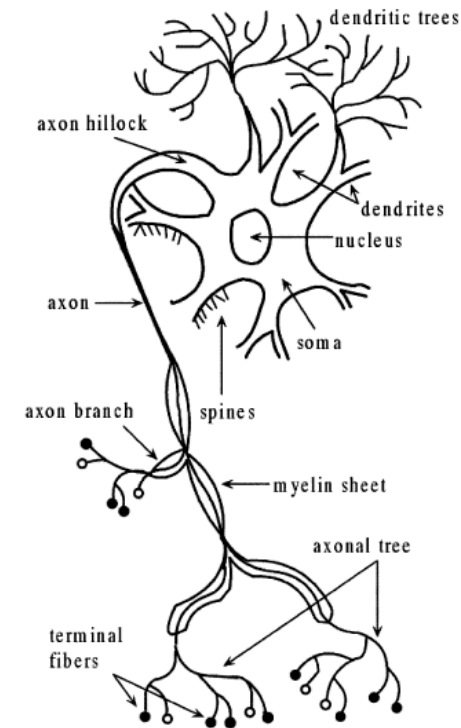


Fig. 1. Diagram of a neuron cell showing dendrites, dendritic trees, axon branches, and terminal branches. Excitatory and inhibitory inputs are indicated, respectively, by black small disks (●) and small circles (○).



# Introduction

- Mathematical morphology for image processing is also a lattice paradigm shift from linear processing (Maragos)
  - Linear translation-invariant (LTI) operators are uniquely represented by linear convolution with the impulse response
  - Erosion (Dilation) translation invariant (ETI(DTI)) operators are uniquely represented by inf-(sup) convolution with the impulse response



# Introduction

$$\begin{aligned}\psi \text{ is LTI} &\Leftrightarrow \psi(F)(x) = (F * H)(x) \\ &= \sum_v F(y)H(x - y)\end{aligned}$$

$$\text{DTI} \quad (F \odot \star H)(x) \triangleq \bigvee_{y \in \mathbb{E}} F(y) \star H(x - y)$$

$$\text{ETI} \quad (F \odot \star' H')(x) \triangleq \bigwedge_{y \in \mathbb{E}} F(y) \star' H'(x - y)$$





# Introduction

- Kinds of processes in Artificial Intelligence

- Filtering

$$\psi : R^N \rightarrow R^N$$

- Dimension reduction

$$\psi : R^N \rightarrow R^d ; d \ll N$$

- Classification (supervised, unsupervised)

$$\psi : R^N \rightarrow \Omega ; \Omega = \{ \omega_1, \dots, \omega_c \}$$



# Introduction

- Kinds of lattice computing
  - Filtering: Mathematical Morphology
  - Dimension reduction: ? ? ? ? ? ? ?
  - Classification- recognition
    - Fuzzy systems
    - Artificial Neural Networks
  - Specific processes
    - Target Localization in images
    - Endmember induction in hyperspectral images



# Introduction

- The learning problem
  - Gradient descent schemas need to compute derivatives of sup, inf functions.
  - Heuristic growing produces overfitting (category explosion) and there is no proof of convergence.
  - Random search algorithms are computationally expensive.



# Some historical landmarks

- 1979
  - R. Cuninghame-Green: Minimax Algebra
- 1982
  - J. Serra: Image Analysis and Mathematical Morphology
- 1991
  - Carpenter, Grossberg: Fuzzy-ART
- 1992
  - Simpson: Min-max Neural Networks
  - Pedrycz: Relational System Learning
- 1995
  - Yang, Maragos: Min-max Classifiers
- 1998
  - Ritter, Sussner: Morphological Associative Memories
  - Gader: Shared-weight Morphological Neural Networks
- 2000
  - Kaburlassos, Petridis: Fuzzy Lattice Neurocomputing
- 2003
  - Ritter: Dendritic Computing
- 2005
  - Kaburlassos: Towards a unified modeling and knowledge representation based on Lattice Theory
  - Maragos: Lattice image processing: a unification of morphological and Fuzzy algebraic systems
- 2007
  - Kaburlassos, Ritter: Computational Intelligence based on Lattice Theory



# Fuzzy ART

Carpenter, Grossberg



# Starting point

- It is an extension of binary input Adaptive Resonance Theory (ART) to continuous variables in  $[0,1]$ :
  - Logical AND, intersection  $\rightarrow$  inf operator
- Coding:
  - appending the complementary  $(1-x_i)$  to each input variable  $x_i$ .
- Category == Cluster

ART 1  
(BINARY)

FUZZY ART  
(ANALOG)



CATEGORY CHOICE

$$T_j = \frac{|\mathbf{I} \cap \mathbf{w}_j|}{\alpha + |\mathbf{w}_j|}$$

$$T_j = \frac{|\mathbf{I} \wedge \mathbf{w}_j|}{\alpha + |\mathbf{w}_j|}$$

MATCH CRITERION

$$\frac{|\mathbf{I} \cap \mathbf{w}|}{|\mathbf{I}|} \geq \rho$$

$$\frac{|\mathbf{I} \wedge \mathbf{w}|}{|\mathbf{I}|} \geq \rho$$

FAST LEARNING

$$\mathbf{w}_j^{(\text{new})} = \mathbf{I} \cap \mathbf{w}_j^{(\text{old})} \quad \mathbf{w}_j^{(\text{new})} = \mathbf{I} \wedge \mathbf{w}_j^{(\text{old})}$$

$\cap$  = logical AND intersection       $\wedge$  = fuzzy AND minimum

Fig. 2. Comparison of ART 1 and fuzzy ART.



# Algorithm Elements

- Category selection based on  $T_j$ 
  - It is a measure of inclusion of the input in the category

$$T_J = \max \{T_j : j = 1 \cdots N\}. \quad (\mathbf{p} \wedge \mathbf{q})_i \equiv \min(p_i, q_i)$$

$$T_j(\mathbf{I}) = \frac{|\mathbf{I} \wedge \mathbf{w}_j|}{\alpha + |\mathbf{w}_j|}, \quad |\mathbf{p}| \equiv \sum_{i=1}^M |p_i|$$





- Resonance: Vigilance parameter  $\rho$ 
  - Decision about the creation of a new category
  - Measure of category compactness: inclusion of the weight  $w_J$  in the input  $I$

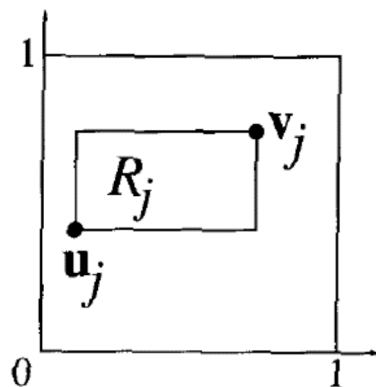
$$\frac{|I \wedge w_J|}{|I|} \geq \rho; \quad \text{Input accepted in the winning category}$$



- Learning

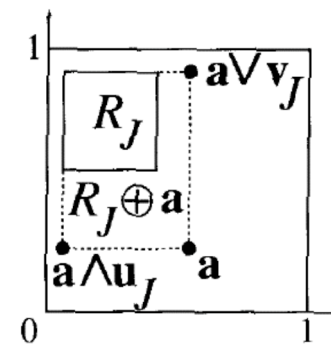
- Enlarging the category enclosing the new data

$$\mathbf{w}_J^{(\text{new})} = \beta \left( \mathbf{I} \wedge \mathbf{w}_J^{(\text{old})} \right) + (1 - \beta) \mathbf{w}_J^{(\text{old})}.$$



(a)

After presentation  
of  $\mathbf{a}$  ( $\beta=1$ ) - - ->



(b)



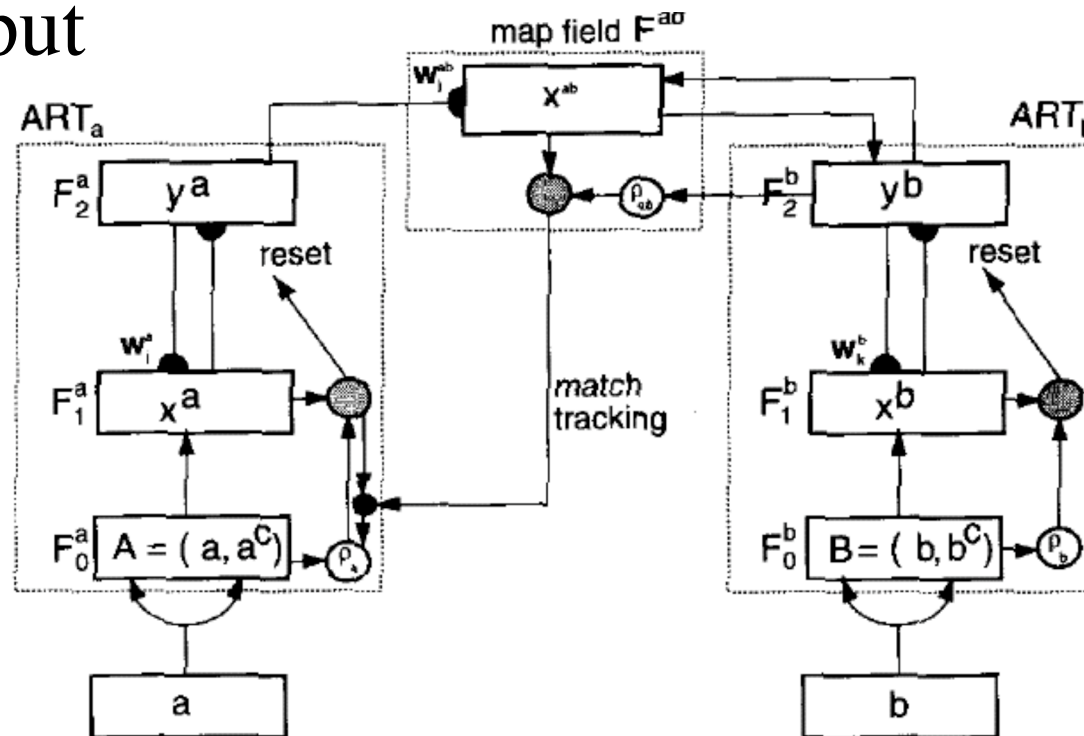
# Fuzzy-ART properties

- Forms hyper-rectangular categories covering the data
- Hyper-rectangles grow monotonically in all dimensions during training
- The size of a category equals  $|R_j| = M - |\mathbf{w}_j|$
- It is bounded by  $|R_j| < M(1 - \rho)$
- If  $0 \leq \rho < 1$  the number of categories is bounded (but most times grows big!)



# Supervised learning ARTMAP

- Encodes and categorizes both input and output



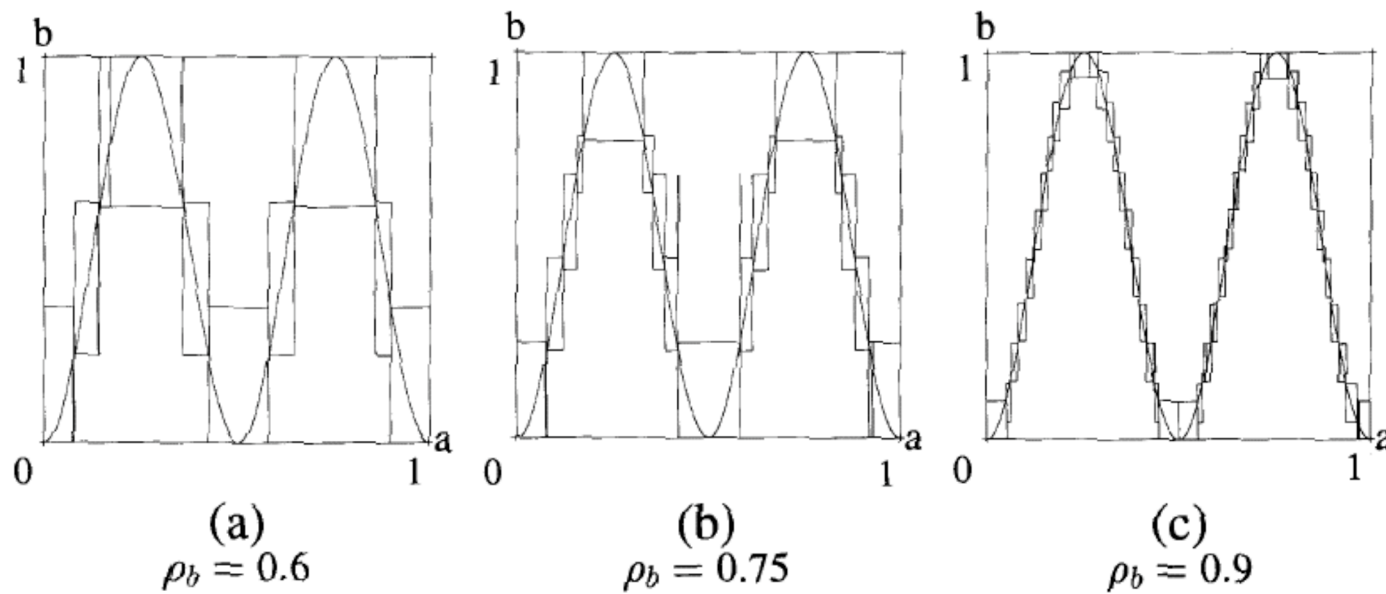


Fig. 12. Incremental approximation of a sinusoidal function for  $ART_b$  vigilance parameters, with  $\rho_b$  equal to (a) 0.6, (b) 0.75, and (c) 0.9. In each simulation the fuzzy ARTMAP system was trained on 1000 randomly chosen points  $a \in [0, 1]$ . Each graph shows the test set confidence intervals  $R_K^b$  selected by the test set points. The maximum lengths of these intervals are (a) 0.4, (b) 0.25, and (c) 0.1. Graph (c), with  $\rho_b = 0.9$ , is close to the asymptotic state of the three graphs in Fig. 11. See Table III.



# Fuzzy-ARTMAP applications

- Control
- Classification and pattern recognition
- Data mining



# Yang, Maragos 1995

## Min-Max classifiers



# Starting point

- Boolean functions in DNF

$$B(\vec{b}), \vec{b} = (b_1, \dots, b_d) \in \{0, 1\}^d, \quad b_i \in \{0, 1\}$$

- Min-max functions are obtained replacing Boolean literals by real-valued variables

$$f: [0, 1]^d \rightarrow [0, 1] \quad x_i \in [0, 1]$$

$$f(x_1, x_2, \dots, x_d) = \bigvee_j \bigwedge_{i \in I_j} l_i, \quad l_i \in \{x_i, 1 - x_i\}$$





- For classification a thresholding step is added

$$\theta \in [0, 1].$$

$$f_{\theta}(\vec{x}) = P[f(\vec{x}) \geq \theta] = \begin{cases} 1 & \text{if } f(\vec{x}) \geq \theta, \\ 0 & \text{otherwise.} \end{cases}$$



# Learning

- Minimization of the Mean Square Error (MSE)

$$\mathcal{E}(t) = E[(z(t) - d(t))^2].$$

- Gradient descent on the function parameters

$$\vec{p}(t + 1) = \vec{p}(t) - \mu \nabla_{\vec{p}} \mathcal{E}(t).$$

- Instantaneous error

$$\vec{p}(t + 1) = \vec{p}(t) - 2\mu(z(t) - d(t))\mu \nabla_{\vec{p}} z(t)$$



- Trick
  - Assume no input variable is complemented
  - Extend the input space to 2d including the complements ... **Fuzzy-ART?**
- Problems
  - Define parameters to allow differentiability
  - Approximate gradient of min, max, threshold



# Functional form

$$h_j = \bigwedge_{i \in I_j} x_i, \quad j = 1, 2, \dots, k \quad \text{clause}$$

$$y = \bigvee_{j=1}^k h_j \quad \text{expression}$$

$$z = \begin{cases} 1 & y \geq \theta, \\ 0 & y < \theta. \end{cases} \quad \text{Decision through threshold}$$



- How to model continuously the conjunctive expression structure:  $I_j$ ?
  - Continuous variables  $m_{ij}$  such that
    - $x_i$  is included in  $I_j$  if  $m_{ij} \geq 0$ ,
    - $x_i$  is excluded from  $I_j$  if  $m_{ij} < 0$ .
  - The **parameters to be learnt**

$$\vec{p}(t) = (\theta(t), m_{11}(t), \dots, m_{d1}(t), \dots, m_{dk}(t)).$$



- Derivative with respect to the threshold

$$\frac{\partial z}{\partial \theta} = \begin{cases} -\frac{1}{2\beta} & \text{if } |y - \theta| \leq \beta, \\ 0 & \text{otherwise.} \end{cases}$$

- Where  $\beta$  is the width of a pulse approximating the derivative of the step function



- Derivative with respect to the structure parameters

$$\frac{\partial z}{\partial m_{ij}} = \frac{\partial z}{\partial y} \frac{\partial y}{\partial h_j} \frac{\partial h_j}{\partial m_{ij}}$$

- Implies the derivative of maximum and minimum functions.



# Derivative of maximum

- Implicit formulation of maximum

$$G(y, h_1, \dots, h_k) = \sum_{j=1}^k \{U_3(y - h_j) - 1\} + \frac{G_e}{2} = 0$$

$$U_3(x) = \begin{cases} 1 & \text{if } x > 0, \\ \frac{1}{2} & \text{if } x = 0, \\ 0 & \text{if } x < 0. \end{cases}$$





- Leads to the following expression

$$\frac{\partial y}{\partial h_j} \approx \begin{cases} \frac{1}{N_{max}} & \text{if } 0 \leq y - h_j \leq \beta \\ 0 & \text{otherwise.} \end{cases}$$

$$\begin{aligned} N_{max} &\stackrel{\Delta}{=} \text{number of } h_j\text{'s such that } y - h_j \leq \beta \\ &= \sum_{j=1}^k U_2(\beta - (y - h_j)). \end{aligned}$$

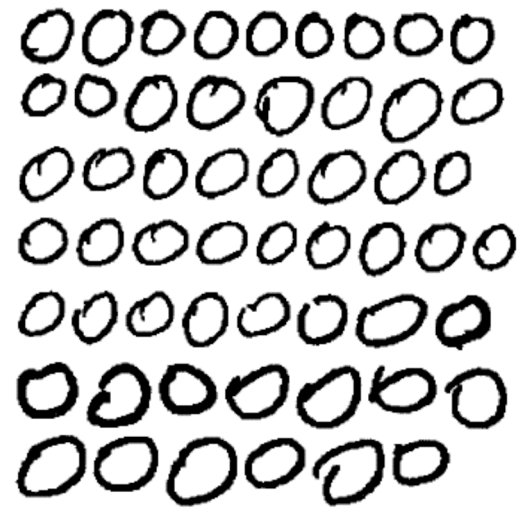


# Results on handwritten digit recognition

Table 1. Results for 0–1 classification problem employing *both* shape-size histograms and Fourier descriptors

| Distinguishing 0's and 1's                                                        |                         |                |         |                                |                |
|-----------------------------------------------------------------------------------|-------------------------|----------------|---------|--------------------------------|----------------|
| Normalized radial size histograms and Fourier descriptors                         |                         |                |         |                                |                |
| No. of minima                                                                     | Min-max % error (train) | % error (test) | Network | Neural network % error (train) | % error (test) |
| 1                                                                                 | 0.083                   | 0.25           | 1,1     | 0.083                          | 0              |
| 3                                                                                 | 0.083                   | 0.25           | 3,1     | 0.083                          | 0              |
| 5                                                                                 | 0.1                     | 0.25           | 5,1     | 0.083                          | 0              |
| 7                                                                                 | 0.083                   | 0.25           | 7,1     | 0.083                          | 0              |
| Normalized shape-size histograms with $2 \times 2$ square and Fourier descriptors |                         |                |         |                                |                |
| 1                                                                                 | 3.867                   | 2.6            | 1,1     | 0.633                          | 1.2            |
| 3                                                                                 | 1.9                     | 2.8            | 3,1     | 0.633                          | 0.85           |
| 5                                                                                 | 1.083                   | 3              | 5,1     | 0.567                          | 0.8            |
| 7                                                                                 | 1.733                   | 3              | 7,1     | 0.533                          | 0.55           |

The top two tables are generated using normalized radial histograms and Fourier descriptors, while the lower two using normalized shape-size histogram with  $2 \times 2$  square and Fourier descriptors.



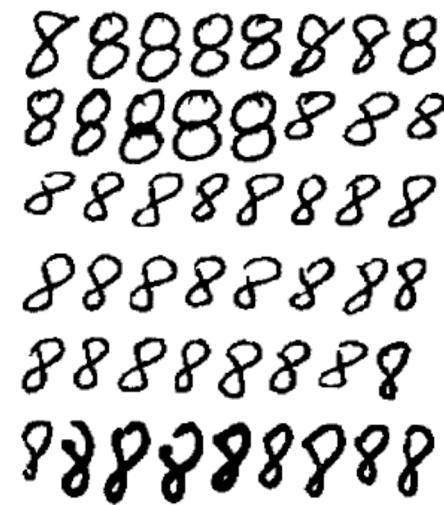
(a)



(b)



(c)



(d)

Fig. 4. Sample data from the handwritten database. (a) A collection of 0's. (b) A collection of 1's. (c) A collection of 6's. (d) A collection of 8's.



# Associative Morphological Memories

Ritter, Sussner



# Starting point

- Linear neuron

$$\tau_i(t+1) = \sum_{j=1}^n a_j(t) \cdot w_{ij} \quad a_i(t+1) = f(\tau_i(t+1) - \theta_i)$$

- Matrix notation

$$T(t+1) = W \cdot \mathbf{a}(t)$$

$$\mathbf{a}(t) = (a_1(t), \dots, a_n(t))'$$

$$T(t+1) = (\tau_1(t+1), \dots, \tau_n(t+1))'$$



- Morphological **dilative** neuron:

$$\tau_i(t+1) = \bigvee_{j=1}^n a_j(t) + w_{ij}$$

- Matrix notation: max product  $T(t+1) = W \boxtimes \mathbf{a}(t)$

$$C = A \boxtimes B$$

$$c_{ij} = \bigvee_{k=1}^p a_{ik} + b_{kj} = (a_{i1} + b_{1j}) \vee (a_{i2} + b_{2j}) \vee \cdots \vee (a_{ip} + b_{pj}).$$



- Morphological **erosive** neuron:

$$\tau_i(t+1) = \bigwedge_{j=1}^n a_j(t) + w_{ij}$$

- Matrix notation: min-product  $T(t+1) = W \boxtimes \mathbf{a}(t)$

$$C = A \boxtimes B$$

$$c_{ij} = \bigwedge_{k=1}^p a_{ik} + b_{kj} = (a_{i1} + b_{1j}) \wedge (a_{i2} + b_{2j}) \wedge \cdots \wedge (a_{ip} + b_{pj}).$$



# Morphological associative memories

- Hopfield associative memory: given an input  $\mathbf{x}$  recalls response  $\mathbf{y}$  as

$$\mathbf{y} = W \cdot \mathbf{x}.$$

- To store  $k$  vector pairs

$(\mathbf{x}^1, \mathbf{y}^1), \dots, (\mathbf{x}^k, \mathbf{y}^k)$ , where  $\mathbf{x}^\xi \in R^n$  and  $\mathbf{y}^\xi \in R^m$

$$W = \sum_{\xi=1}^k \mathbf{y}^\xi \cdot (\mathbf{x}^\xi)'$$





- The Hopfield associative memory provides **perfect recall** if the input patterns are orthogonal
- If they are not orthogonal, the recall is corrupted by crosstalk noise.



- Morphological Associative Memories
- Construction with a single pair:

$$W = \mathbf{y} \boxtimes (-\mathbf{x})'$$

- Recall (perfect):

$$W \boxtimes \mathbf{x} = \mathbf{y}$$



- Given a set of input-output patterns

$$\{(\mathbf{x}^\xi, \mathbf{y}^\xi) : \xi = 1, \dots, k\}$$

- Define:  $(X, Y)$ ,

$$X = (\mathbf{x}^1, \dots, \mathbf{x}^k) \quad Y = (\mathbf{y}^1, \dots, \mathbf{y}^k).$$

- Two natural morphological memories

$$W_{XY} = \bigwedge_{\xi=1}^k [\mathbf{y}^\xi \times (-\mathbf{x}^\xi)'] \quad \text{and} \quad M_{XY} = \bigvee_{\xi=1}^k [\mathbf{y}^\xi \times (-\mathbf{x}^\xi)'].$$



- Basic recall property:
  - the erosive and dilative memory recalls bound the exact response

$$W_{XY} \leq y^\xi \times (-x^\xi)' \leq M_{XY}$$

$$W_{XY} \boxminus x^\xi \leq y^\xi \leq M_{XY} \boxplus x^\xi$$

$$W_{XY} \boxminus X \leq Y \leq M_{XY} \boxplus X.$$



- Conditions for perfect recall

*Theorem 2:*  $W_{XY}$  is  $\square$ -perfect for  $(X, Y)$  if and only if for each  $\xi = 1, \dots, k$ , each row of the matrix  $[\mathbf{y}^\xi \times (-\mathbf{x}^\xi)'] - W_{XY}$  contains a zero entry. Similarly  $M_{XY}$  is  $\square$ -perfect for  $(X, Y)$  if and only if for each  $\xi = 1, \dots, k$ , each row of the matrix  $M_{XY} - [\mathbf{y}^\xi \times (-\mathbf{x}^\xi)']$  contains a zero entry.



# Autoassociative memories

- When  $X=Y$ , memories  $W_{XX}$  and  $M_{XX}$  are called autoassociative.
- They have perfect recall and unlimited capacity

$$W_{XX} \boxtimes X = X \text{ and } M_{XX} \boxdot X = X.$$

- Recalling converges in one step



# Noise

- Memory  $W_{XX}$  is robust to erosive noise and sensitive to dilative noise
- Memory  $M_{XX}$  is robust to dilative noise and sensitive to erosive noise

$$\tilde{\mathbf{x}}^\gamma \leq \mathbf{x}^\gamma \quad \text{Erosive noise}$$

$$\tilde{\mathbf{x}}^\gamma \geq \mathbf{x}^\gamma \quad \text{Dilative noise}$$

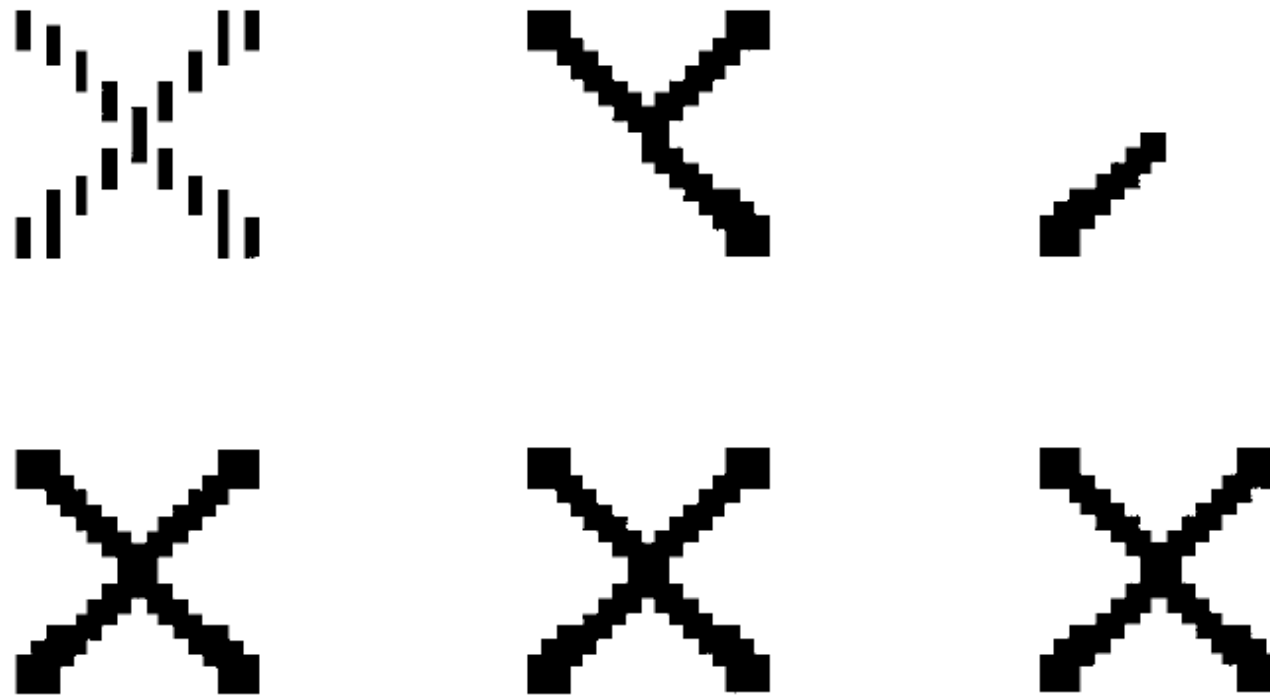


Fig. 4. The top row shows the corrupted input patterns and the bottom row the corresponding output patterns of the morphological memory  $W_{XX}$ .



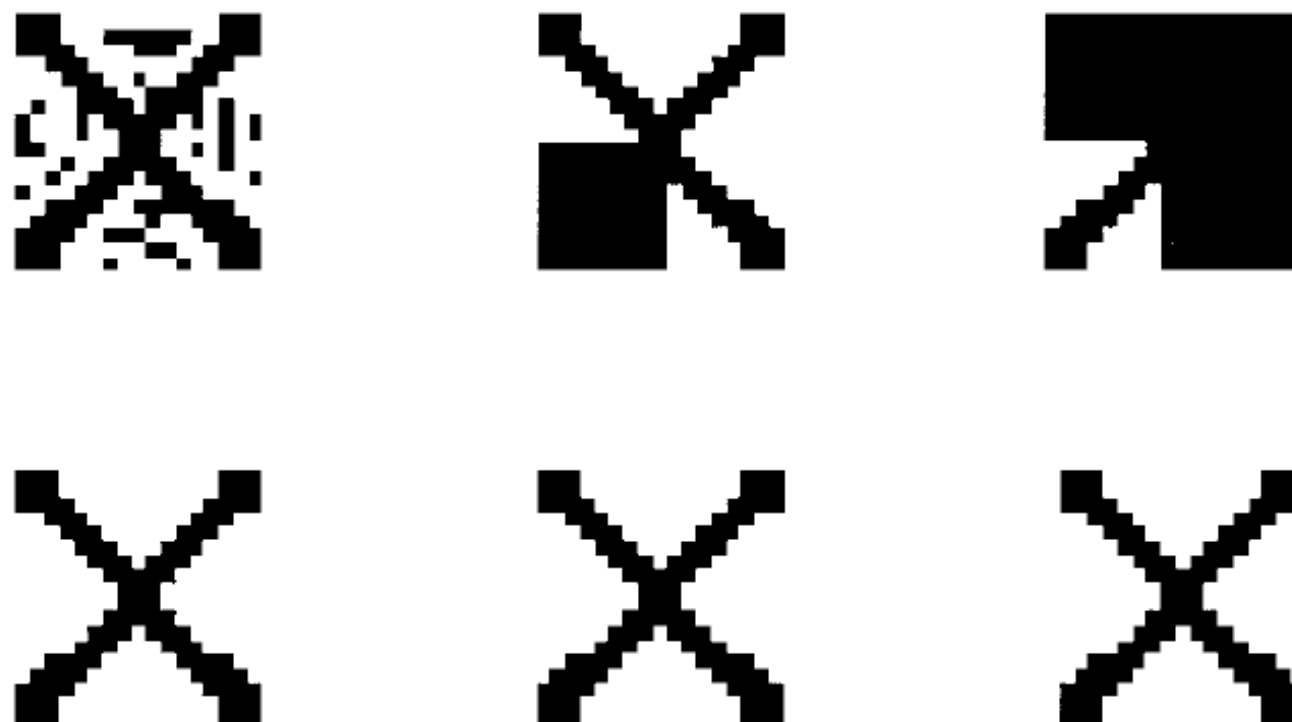


Fig. 5. The top row shows the corrupted input patterns and the bottom row the corresponding output patterns of the morphological memory  $M_{XX}$ .



# Approaches to solve the noise problem

- Definition of kernels

*Definition 2:* Let  $Z = (\mathbf{z}^1, \mathbf{z}^2, \dots, \mathbf{z}^k)$  be an  $n \times k$  matrix. We say that  $Z$  is a *kernel* for  $(X, Y)$  if and only if the following two conditions are satisfied:

1.  $M_{ZZ} \boxtimes X = Z$ ;
2.  $W_{ZY} \boxtimes Z = Y$ .

It follows that if  $Z$  is a kernel for  $(X, Y)$ , then

$$W_{ZY} \boxtimes (M_{ZZ} \boxtimes X) = W_{ZY} \boxtimes Z = Y.$$

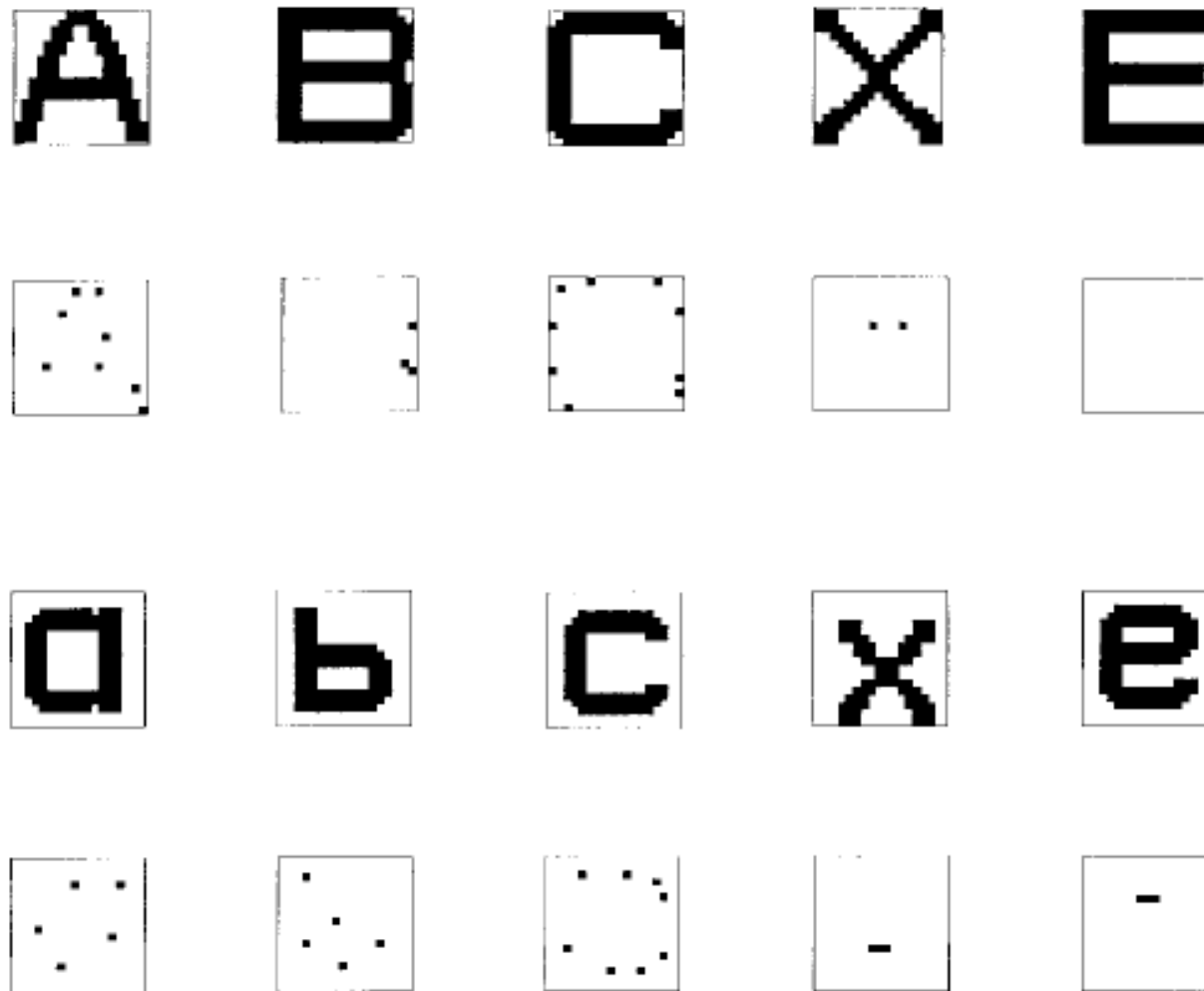


Fig. 6. An example of kernel images. The kernel image corresponding to a particular letter image is the image directly below the letter image.

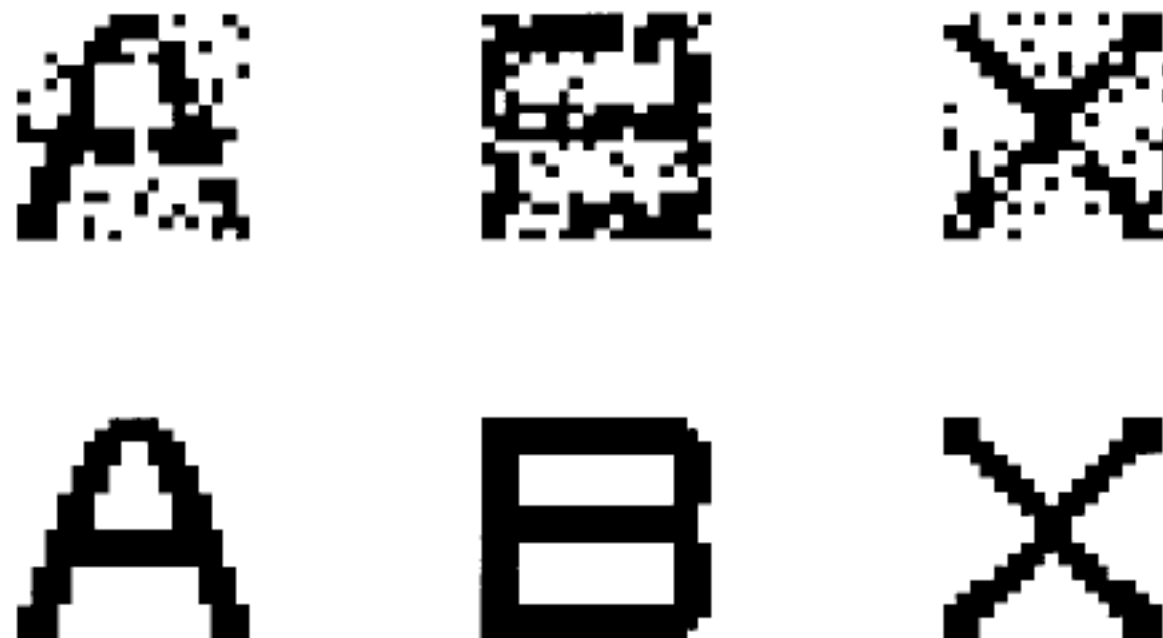


Fig. 7. An example of the behavior of the memory  $\{input \rightarrow M_{ZZ} \rightarrow W_{ZY} \rightarrow output\}$ . The memory was trained using the ten exemplars shown in Fig. 2. Presenting the memory with the corrupted patterns of the letters A, B, and X resulted in perfect recall (lower row). Each letter was corrupted by randomly reversing each bit with a probability of 0.15.



# Lattice Image Processing: A Unification of Morphological and Fuzzy Algebraic Systems

P. Maragos



# Starting point

- Design of new filters: generalized opening and closing
- Works on the lattice of functions

$$\mathcal{S} = \mathbb{V}^E \quad F : E \rightarrow \mathbb{V}$$

$$F \leq G \Leftrightarrow F(x) \leq G(x) \quad \forall x \in E$$

Inherited partial order

$$\left( \bigvee_{i \in J} F_i \right)(x) \triangleq \bigvee_{i \in J} F_i(x), \quad x \in E$$

Inherited supremum  
and infimum

$$\left( \bigwedge_{i \in J} F_i \right)(x) \triangleq \bigwedge_{i \in J} F_i(x), \quad x \in E$$



# Increasing operators

$\delta$  is **dilation** iff  $\delta(\bigvee_{i \in J} X_i) = \bigvee_{i \in J} \delta(X_i)$

$\varepsilon$  is **erosion** iff  $\varepsilon(\bigwedge_{i \in J} X_i) = \bigwedge_{i \in J} \varepsilon(X_i)$

$\alpha$  is **opening** iff  $\alpha$  is increasing, idempotent & anti-extensive

$\beta$  is **closing** iff  $\beta$  is increasing, idempotent & extensive



# Adjunction

- The operator pair  $(\varepsilon, \delta)$  is an **adjunction** if

$$\delta(X) \leq Y \Leftrightarrow X \leq \varepsilon(Y) \quad \forall X, Y \in \mathcal{L}$$

- An adjunction defines a pair of morphological filters

*$\delta\varepsilon$  is an opening, and  $\varepsilon\delta$  is a closing.*





# Signal processing

- Algebraic structure of the scalars:

$$(\mathbb{V}, \vee, \wedge, \star, \star')$$

- Complete lattice-ordered double monoid
  - Addition  $\vee$
  - Dual addition  $\wedge$
  - Multiplication  $\star$
  - Dual multiplication  $\star'$



# Signal processing

- The space of signals is a function lattice

$$\mathcal{S} = \text{Fun}(E, \mathbb{V})$$

- It inherits the clodum structure of the scalars, with appropriate natural definitions of addition and multiplication



# Parallelism to linear processing

- Representation of a signal as a supremum (infimum) of translated impulses

$$F(x) = \bigvee_{y \in E} F(y) \star q_y(x) = \bigwedge_{y \in E} F(y) \star' q'_y(x)$$



- Linear superposition principle

$$\psi \left( \sum_{i \in J} a_i \cdot F_i \right) = \sum_{i \in J} a_i \cdot \psi(F_i)$$

- Nonlinear superposition principle

$$\delta \left( \bigvee_{i \in J} c_i \star F_i \right) = \bigvee_{i \in J} c_i \star \delta(F_i),$$



- Translation invariant operator: commutes with all translations

$$\tau \in \mathbb{T}; \text{ i.e. } \psi \tau = \tau \psi.$$

- Nonlinear convolutions define the effect of Erosion and Dilation translation invariant systems



$$\begin{aligned}\psi \text{ is LTI} &\Leftrightarrow \psi(F)(x) = (F * H)(x) \\ &= \sum_y F(y)H(x - y)\end{aligned}$$

$$\text{DTI} \quad (F \odot_{\star} H)(x) \triangleq \bigvee_{y \in \mathbb{E}} F(y) \star H(x - y)$$

$$\text{ETI} \quad (F \odot_{\star'} H')(x) \triangleq \bigwedge_{y \in \mathbb{E}} F(y) \star' H'(x - y)$$



# Generalized convolution adjunctions

- using scalar adjunctions  $(\lambda_{H(x-y)}^{\leftarrow}, \lambda_{H(x-y)})$
- It is possible to obtain the adjoint operator

$$\Delta_H(F)(x) = \bigvee_{y \in \mathbb{E}} F(y) \star H(x - y) = \bigvee_{y \in \mathbb{E}} \lambda_{H(x-y)}(F(y))$$

- Which looks like a correlation

$$\mathcal{E}_H(G)(x) = \bigwedge_{y \in \mathbb{E}} G(y) \star [H(y - x)]^*$$



# Lattice operators using fuzzy norms

- Fuzzy intersection norm --> scalar dilation

$$T: [0, 1]^2 \rightarrow [0, 1]$$

F1.  $T(a, 1) = a$  and  $T(a, 0) = 0$

F2.  $T(a, T(b, c)) = T(T(a, b), c)$  (associativity).

F3.  $T(a, b) = T(b, a)$  (commutativity).

F4.  $b \leq c \Rightarrow T(a, b) \leq T(a, c)$  (increasing).

F5.  $T$  is a continuous function.





- Fuzzy union norm --> scalar erosion

$$U: [0, 1]^2 \rightarrow [0, 1]$$

$$F1'. U(a, 0) = a \text{ and } U(a, 1) = 1.$$



- Translations under the fuzzy framework

$$\mathcal{S} = \text{Fun}(\mathbb{E}, [0, 1])$$

$$\tau_{h,v}(f)(x) = T(f(x - y), v)$$

$$\tau'_{h,v}(f)(x) = U(f(x - y), v)$$

$$(h, v) \in \mathbb{E} \times [0, 1]$$



- Signal representation with fuzzy translations

$$\begin{aligned} f(x) &= \bigvee_y T[q(x - y), f(y)] \\ &= \bigwedge_y U[q'(x - y), f(y)] \end{aligned}$$

$$q(x) \triangleq \begin{cases} 1, & x = \vec{0} \\ 0, & x \neq \vec{0} \end{cases}, \quad q'(x) \triangleq \begin{cases} 0, & x = \vec{0} \\ 1, & x \neq \vec{0} \end{cases}$$



- Translation invariant signal fuzzy **dilations** and **erosions** with sup- $T$  and inf- $U$  convolutions

$$(f \circ_T g)(x) \triangleq \bigvee_y T[g(x - y), f(y)],$$

$$(f \circ'_U g)(x) \triangleq \bigwedge_y U[g(x - y), f(y)]$$



- Fuzzy dilation adjoint  $\Delta_{H,T}(F)(x) \triangleq (F \circ_T H)(x)$

$$\mathcal{E}_{H,\Omega}(G)(y) \triangleq \bigwedge_{x \in \mathbb{E}} \Omega[H(x - y), G(x)]$$

where  $\Omega[H(x - y), G(x)]$  is actually the adjoint of the fuzzy  $T$ -norm:

$$T(a, v) \leq w \Leftrightarrow v \leq \Omega(a, w)$$

$$\Omega(a, w) = \sup\{v \in [0, 1] : T(a, v) \leq w\}$$



# Example norms

## Fuzzy intersection norm

$$\text{Min : } T_1(a, v) = \min(a, v)$$

$$\text{Product : } T_2(a, v) = a \cdot v$$

$$\text{Yager : } T_3(a, v) = 1 - (1 \wedge [(1 - v)^p + (1 - a)^p]^{1/p}), \quad p > 0.$$

## Adjoint norm

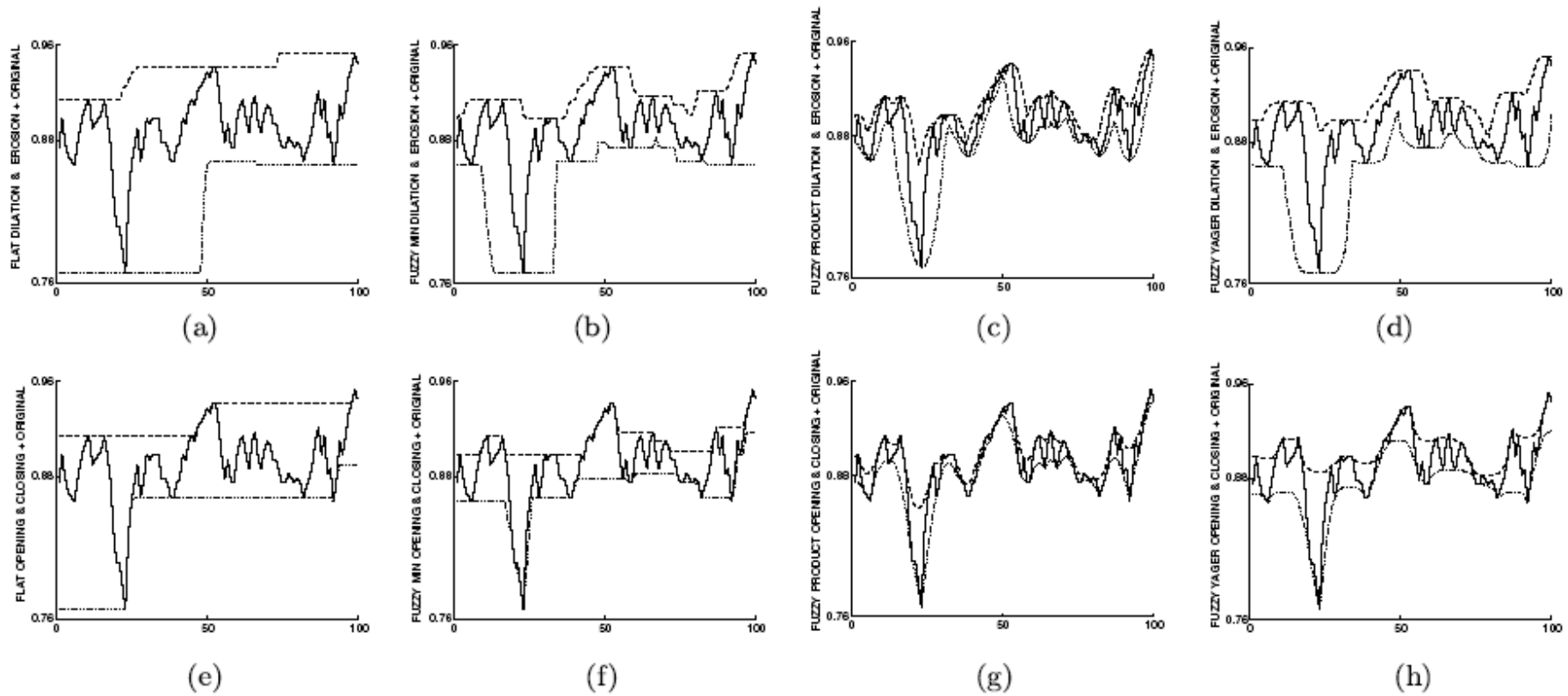
$$\Omega_1(a, w) = \begin{cases} w, & w < a \\ 1, & w \geq a \end{cases}$$

$$\Omega_2(a, w) = \begin{cases} \min(w/a, 1), & a > 0 \\ 1, & a = 0 \end{cases}$$

$$\Omega_3(a, w) = \begin{cases} 1 - [(1 - w)^p + (1 - a)^p]^{1/p}, & w < a \\ 1, & w \geq a \end{cases}$$



# Results



*Figure 1.* Comparison of 1D basic morphological and lattice-fuzzy signal operators. Rows 1 and 2, left to right: flat, minimum, product, Yager. Row 1: original signal (solid line), dilation (dashed line), erosion (dotted line). Row 2: closing (dashed line), opening (dotted line). Courtesy of [27].



# Modelling and Knowledge representation based in Lattice Theory

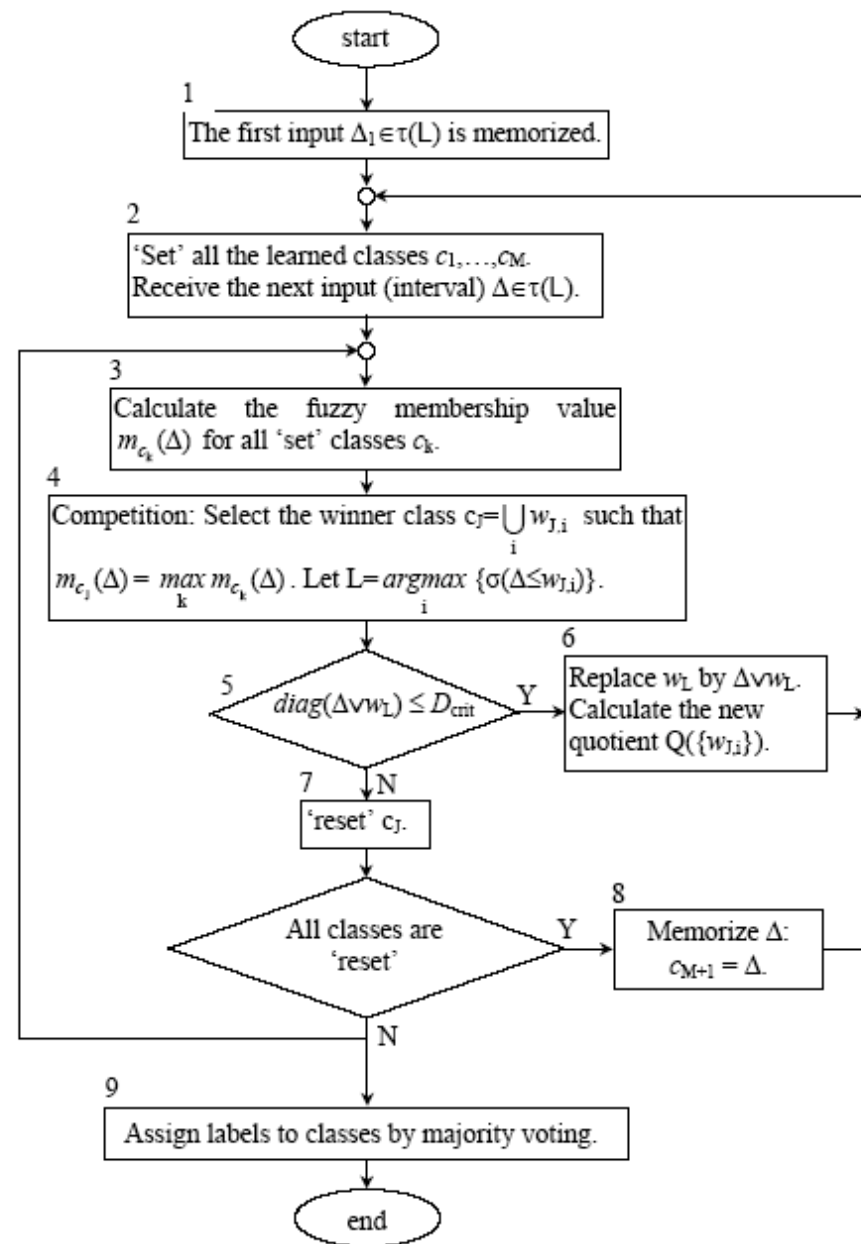
V. G. Kaburlasos





# Starting point

- Generalizes the Fuzzy-ART and Fuzzy-ARTMAP architectures
- The Fuzzy Lattice Neurocomputing
  - Proposes an abstract representation (FIN) based on generalized interval (GI).
  - Is defined based on inclusion measures and distances on the FINs



Inclusion measure

$$\sigma(\Delta \leq w_{j,i})$$

Vigilance parameter

$$D_{crit}$$

learning

$$\Delta \vee w_L$$

Fig.7-1 Flowchart of algorithm  $\sigma$ -FLN for learning (training).



# Advantages of $\sigma$ -FLN

- Deals with data uncertainty
- Different positive valuation functions
- Deals with disparate (lattice) data types
- *Missing* and *don't care* values are treated naturally: least and greatest lattice elements.
- Learning in one step, **presentation order dependent**



# Intervals in the unit hypercube

- Lattice interval corresponds to a hyperbox

$$\Delta = [a, b] = [(a_1, \dots, a_N), (b_1, \dots, b_N)] = [a_1, b_1, \dots, a_N, b_N],$$

- Positive valuation function

$$v(w) = v(\theta(p)) + v(q) = N + \sum_{i=1}^N (q_i - p_i)$$

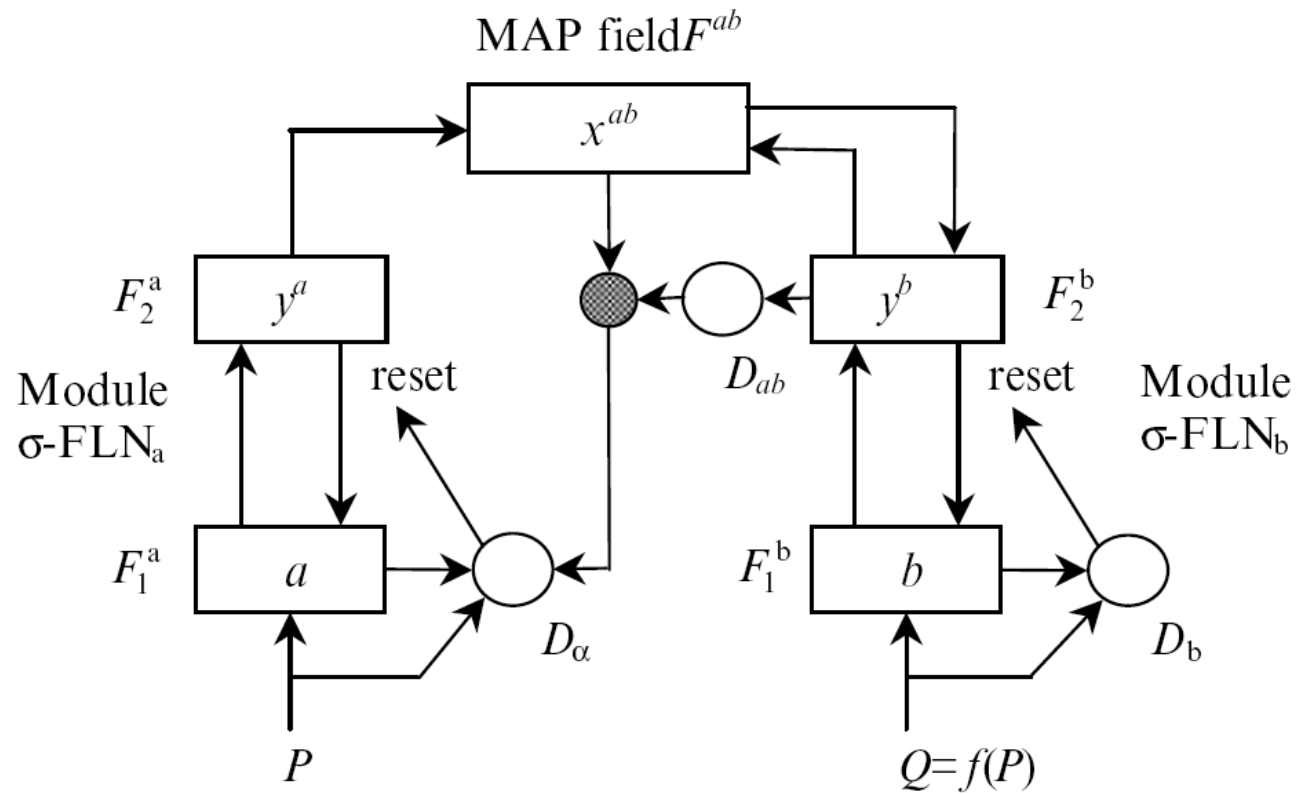
- Lattice join

$$\begin{aligned} \Delta \vee w &= [a_1, b_1, \dots, a_N, b_N] \vee [p_1, q_1, \dots, p_N, q_N] = \\ & [a_1 \wedge p_1, b_1 \wedge q_1, \dots, a_N \vee p_N, b_N \vee q_N]. \end{aligned}$$



- Degree of inclusion

$$\sigma(\Delta \leq w) = \frac{v(\theta(p)) + v(q)}{v(\theta(a \vee p) + v(b \vee q))} = \frac{N + \sum_{i=1}^N (v_i(q_i) - v_i(p_i))}{N + \sum_{i=1}^N [v_i(b_i \vee q_i) - v_i(a_i \wedge p_i)]}.$$



**Fig.7-4** The  $\sigma$ -FLNMAP neural network for inducing a function  $f: \tau(\mathbf{L}) \rightarrow \tau(\mathbf{K})$ , where both  $\mathbf{L}$  and  $\mathbf{K}$  are mathematical lattices.



# Generalization

- Positive Valuation function on a lattice  $(L, \leq)$  satisfies

$$v(x) + v(y) = v(x \wedge y) + v(x \vee y)$$

$$x < y \Rightarrow v(x) < v(y)$$

- A positive valuation in a lattice  $(L, \leq)$  induces a metric (distance)  $d : L \times L \rightarrow R_0^+$

$$d(x, y) = v(x \vee y) - v(x \wedge y)$$



- An inclusion measure is a function  $\sigma : L \times L \rightarrow [0,1]$  satisfying
  - (IM1)  $\sigma(x, x) = 1, \forall x \in L$
  - (IM2)  $x \wedge y < x \Rightarrow \sigma(x, y) < 1$
  - (IM3)  $u \leq w \Rightarrow \sigma(x, u) \leq \sigma(x, w)$
- If  $v$  is a positive valuation in lattice  $(L, \leq)$  then both expressions are inclusion measures

$$(a) \quad k(x, u) = \frac{v(u)}{v(x \vee u)} \quad (b) \quad k(x, u) = \frac{v(x \wedge u)}{v(x)}$$





# Fuzzy Interval Numbers (FIN)

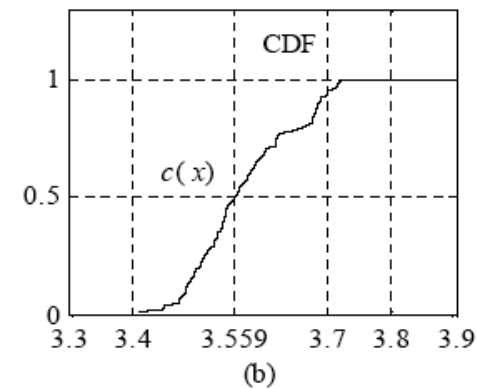
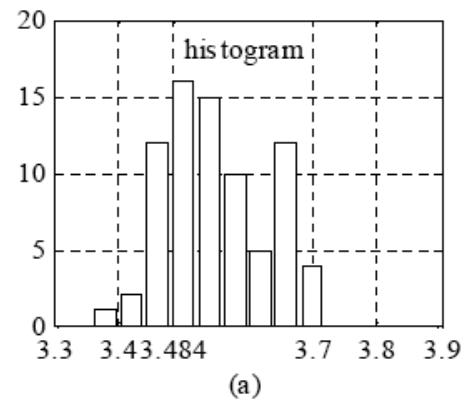
- A **FIN** is a function  $F : (0,1] \rightarrow M$  such that
  - (1)  $F(h) \in M^h$
  - (2) either  $F(h) \in M_+^h$  or  $F(h) \in M_-^h$
  - (3)  $h_1 \leq h_2 \Rightarrow \{x : F(h_1) \neq 0\} \supseteq \{x : F(h_2) \neq 0\}$
- where  $M^h$  denotes the set of generalized intervals of height  $h$ . It is a **lattice ordered linear space**.



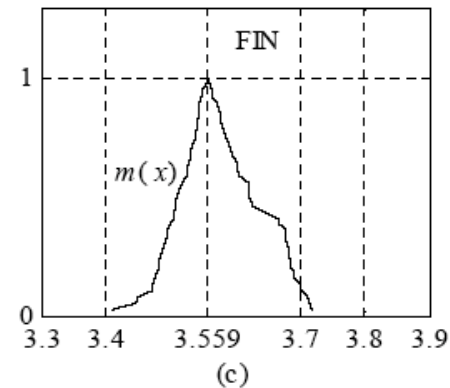
- FINs can be models of
  - Real numbers
  - Intervals
  - Fuzzy numbers
  - Probability distributions
- FINs inherit valuation, inclusion, metric functions from the set of generalized intervals



# Probability distribution FIN



$$m(x) = \begin{cases} 0.5c(x), & x \leq 3.559 \\ 1-0.5c(x), & x > 3.559 \end{cases}$$





# Applications

- Classification and clustering
  - Benchmark problems
  - Epidural surgery planification
  - Orthopedics bone drilling
  - Ambient ozone estimation
  - Prediction of industrial sugar production



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**Table 8-8** Recognition results for the Sonar benchmark data set.

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| <u>Method</u>                       | <u>% Right on Testing</u> |
|-------------------------------------|---------------------------|
| $\sigma$ -FLNMAP for classification | 96.15                     |
| $\sigma$ -FLN for clustering        | 94.23                     |
| Fuzzy ARAM                          | 94.20                     |
| K-Nearest Neighbor                  | 91.60                     |
| BackProp: Angle-Dep. <sup>(1)</sup> | 90.40                     |
| Nearest Neighbor                    | 82.70                     |
| BackProp: Angle-Ind. <sup>(2)</sup> | 77.10                     |

---

(1) Angle Dependent data ordering. (2) Angle Independent data ordering.



**Table 9-3** Performance of various methods on the Forest Covertype benchmark data set. The last column shows the number of induced rules.

| <u>Method</u>                | <u>% Correct</u> | <u>no. of rules</u> |
|------------------------------|------------------|---------------------|
| Backpropagation              | 70               | (6600)              |
| FLNff                        | 68.25            | 654                 |
| FLNmtf                       | 66.27            | 1566                |
| FLNotf                       | 66.13            | 516                 |
| FLNsf                        | 66.10            | 503                 |
| FLNtf                        | 62.58            | 3684                |
| Linear discriminant analysis | 58               | -                   |



# Conclusions



# Conclusions

- Lattice computing defined as computing on the lattice algebra  $(R, \wedge, \vee, +)$  has been maintaining its appeal in the last fifteen years.





# Conclusions

- Application of lattice theory leads to new computational paradigms arising from
  - Fusion of established paradigms
    - Mathematical morphology and fuzzy systems
    - Neural networks and fuzzy systems
  - Generalization of approaches
    - Fuzzy Lattice Neurocomputing



# Future

- Lattice theory may be the formal framework for the development of new approaches:
  - Feature extraction based on linear unmixing based on the identification of endmembers in the data set.
  - Fusion of stochastic models (Random Markov Fields, Hidden Markov Models) and Fuzzy Systems.



Thank you for your attention