

Validation of a Hyperspectral Content-Based Information Retrieval (RS-CBIR) System upon scarce data

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Outline

- 1 Introduction
 - CBIR systems
 - Hyperspectral images
- 2 Hyperspectral CBIR system
 - Spectral features extraction
 - Hyperspectral CBIR
- 3 Hyperspectral CBIR validation strategy
 - CBIR quality assessment
 - Proposed validation strategy
- 4 Experiments and results

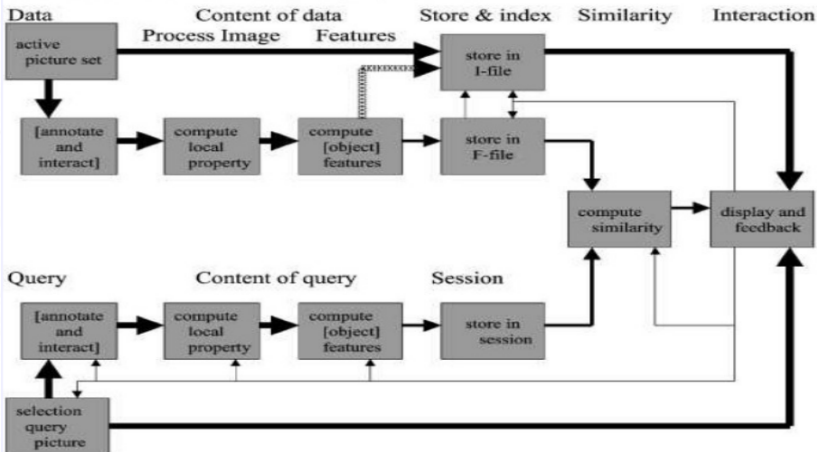
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CBIR systems

- Recover image/multimedia information from large databases using the own images content.
- Solve traditional metadata-based problems.
- Information characterized by low level features (color, textures, shape, ...).
- Compare image dissimilarities by distance functions computed over the features.
- Improve searches by user interaction (Retrieval feedback, Active Learning).

Diagram

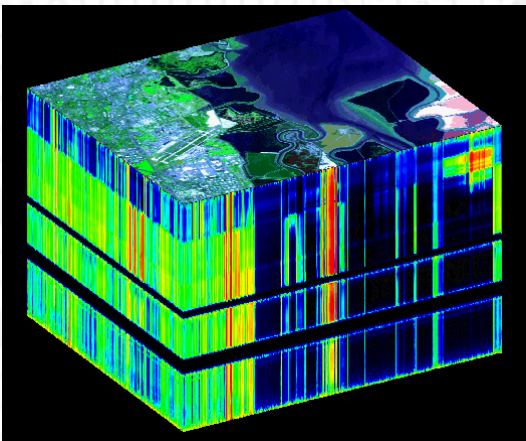


* From "Content-Based Image Retrieval at the end of the early years". W.M.Smeulder et al. IEEE Trans. on Pattern Analysis and Machine Intelligence (2000)

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Hyperspectral cube



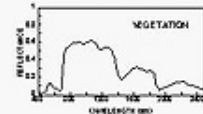
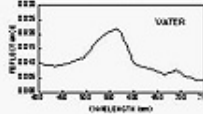
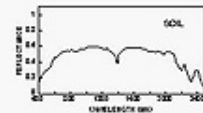
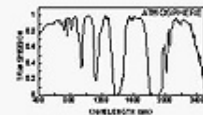
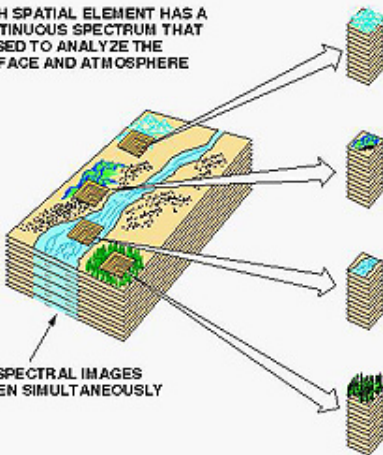
Hyperspectral remote sensing

JPL

AVIRIS CONCEPT

EACH SPATIAL ELEMENT HAS A CONTINUOUS SPECTRUM THAT IS USED TO ANALYZE THE SURFACE AND ATMOSPHERE

224 SPECTRAL IMAGES TAKEN SIMULTANEOUSLY



Color/multispectral - Hyperspectral differences

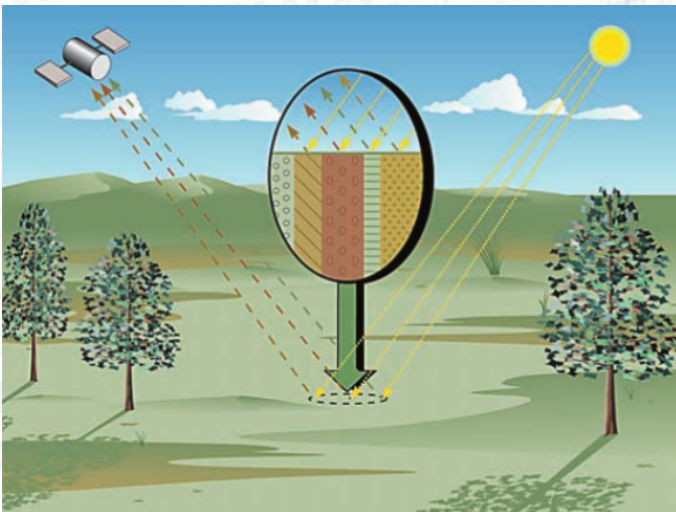
- Bands:
 - Color/Multispectral: 3-10 bands.
 - Hyperspectral: >100.
- Spectral resolution (wavelength/bandwidth):
 - Color/Multispectral: order 10 (low).
 - Hyperspectral: order 100 (high).
- Contiguity:
 - Color/Multispectral: irregular / overlapping.
 - Hyperspectral: regular / non-overlapping.

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Linear Mixing Model

Illustration



Linear Mixing Model

Formulation

LMM

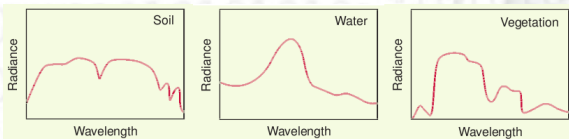
- $H = A \cdot E + \eta$
- $\mathbf{h}(\mathbf{x}, \mathbf{y}) = a(x, y)_1 \cdot \mathbf{e}_1 + a(x, y)_2 \cdot \mathbf{e}_2 + \dots + a(x, y)_p \cdot \mathbf{e}_p + \eta$

where:

- H is an hyperspectral image.
- E is a set with the materials spectral signs (endmembers): spectral information.
- A is a set of fractional abundances images, one for each endmember: spatial information.
- η is additive noise.

Endmembers induction

- Find by automatic unsupervised methods the spectral signs (endmembers) of the material on the image.

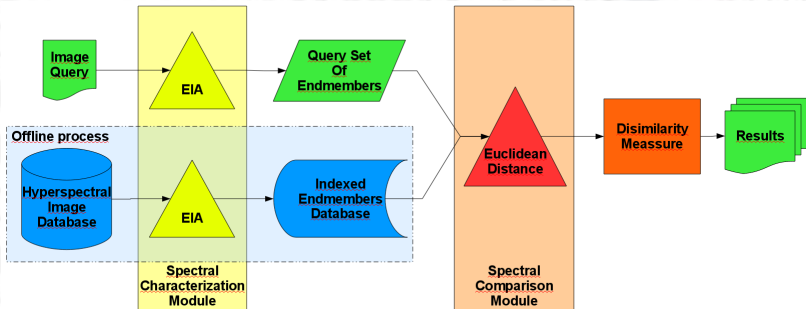


- Each hyperspectral image H_α is characterized by its induced set of endmembers $E_\alpha = \{\mathbf{e}_1, \dots, \mathbf{e}_{p_\alpha}\}$, where p_α is the number of induced endmembers from α -th image.

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Diagram



Spectral distances

- The matrix of distances between two sets of endmembers E_α and E_β is given by

$$D = \{d_{ij}\}; i = 1, \dots, p_\alpha; j = 1, \dots, p_\beta$$

where d_{ij} can be, for instance, the Euclidean distance, d_{euc} , or the angular distance, a.k.a. Spectral Angle Mapper, d_{sam} :

$$d_{euc}(\mathbf{e}_1, \mathbf{e}_2) = \sqrt{\sum_{\lambda=1}^q (e_1^\lambda - e_2^\lambda)^2}$$

$$d_{sam}(\mathbf{e}_i, \mathbf{e}_j) = \cos^{-1} \left(\frac{\sum_{\lambda=1}^q (e_i^\lambda e_j^\lambda)}{\sqrt{\sum_{\lambda=1}^q (e_i^\lambda)^2} \sqrt{\sum_{\lambda=1}^q (e_j^\lambda)^2}} \right)$$

Spectral dissimilarity

- Compare two hyperspectral images H_α, H_β by their spectral features:

$$s(H_\alpha, H_\beta) \equiv s(E_\alpha, E_\beta) = (m_r + m_c) (|p_\alpha - p_\beta| + 1)$$

where m_r and m_c are the mean of the vectors of minimal values of the distance matrix, D , computed by rows and columns respectively.

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Evaluation metrics

- The two most used evaluation measures are *precision* and *recall*.
 - Precision, p , is the fraction of the retrieved images that are relevant to the query.
 - Recall, q , is the fraction of retrieved relevant images respect to the total number of relevant images in the database according to a priori knowledge.
- If we denote T the set of returned images and R the set of all the images relevant to the query, then

$$p = \frac{|T \cap R|}{|T|} \quad q = \frac{|T \cap R|}{|R|}$$

- Results are usually summarized as precision-recall or precision-scope curves.

Problems

- Lack of ground truth knowledge (predefined categories):
 - Due to the expensive, tedious and error prone ground truth gathering process.
 - Well known problem in RS classification.
- Users difficulties to evaluate the retrieved images giving a positive/negative feedback:
 - Specific problem of CBIR systems in a Remote Sensing context.
 - RS images are not easily interpreted by visual inspection.
 - RS-CBIR feedback retrieval requires domain-specific skills and new interaction methodologies yet to be developed.

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Proposed strategy

- Use the RS data inherent structures to simulate potential users queries.
- We propose to build the groundtruth of a potential query by a clustering process.
- Thus, the groundtruth modeled by a clustering process is a relevant set $R(q_i) = \{x_{i_1}, \dots, x_{i_k}\}$ where $q_i = \{x_i\}$ is the query, and images $\{x_{i_1}, \dots, x_{i_k}\}$ belong to the same cluster than x_i .
- The set of all the queries, $Q = \{q_i\}_{i=1}^n$, represents a simulated family of queries whose groundtruth is given by a clustering process.

Hyperspectral CBIR validation

- Precision and recall quality measures can be given using the proposed relevant set $R(q_i) = \{x_{i_1}, \dots, x_{i_k}\}$.
- The ideal response of a CBIR system M to a potential query q_i is a ranked list given by

$$f_M(q_i) = \{x_{i'_1}, \dots, x_{i'_k}, x_{i'_{k+1}}, \dots, x_{i'_n}\}$$

where $\{x_{i'_1}, \dots, x_{i'_k}\}$ is any permutation of the images belonging to the relevant set $R(q_i)$.

Hyperspectral database

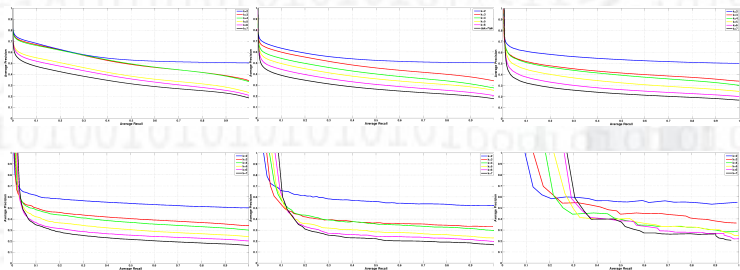
- We applied the Hyperspectral CBIR over a scene provided by HyVista Corp. and DLRs optical Airborne Remote Sensing and Calibration Facility service.
- The scene is a big image of 2878×512 pixels and 125 spectral bands.
 - Twelve bands corresponding to water absorption bands have been removed, remaining 113 bands.
- The image has been captured over the DLR facilities in Oberpfaffenhofen (Germany), and consist mainly of vegetation and fields, in addition to the DLR facilities and some small towns buildings.
- We built six datasets by cutting the scene in patches of increasing sizes, from 8×8 pixels (23040 patches) up to 256×256 pixels (24 patches).

Potential queries simulation

- For each dataset we performed several clusterings on the average radiance of each patch sample by means of the ELGB clustering algorithm.
 - Different values of the number of clusters, $k = 2, \dots, 7$.
 - The ELGB is an enhanced k-means clustering algorithm which has a strong robustness against initial condition variations.
- For each dataset and cluster, the mean and standard deviation were calculated in order to purge those patches away from two times the standard deviation.
 - Eliminating ambiguous samples.
- Each clustering is assumed to be the ground truth of the expected response to a simulated family of queries, against which the RS-CBIR must compete.

Results

- Precision/recall curves for the different datasets:



- Decrease on the performance of the Hyperspectral CBIR system as the diversity of the simulated queries, given by the number of clusters k , increases.
- The size of the images does not affect significantly the performance of the Hyperspectral CBIR system.

Summary

- There is a big need of new strategies to validate RS-CBIR systems that could successfully overcome the lack of ground truth data.
- We have developed a methodology for RS-CBIR systems quality assessment, inspired in the DAMA strategy for unsupervised segmentation quality assessment in remote sensing images.
 - Our methodology works when little or no ground truth data are available.
- We show an example of its applicability to test a Hyperspectral CBIR system.

Thanks

- Contact:

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