

# Neurocognitive disorder detection based on Feature Vectors extracted from VBM analysis of structural MRI

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## Abstract

Dementia is a growing concern due to the aging process of the western societies. Non-invasive detection is therefore a high priority research endeavor. In this paper we report results of classification systems applied to the feature vectors obtained by a feature extraction method computed on Structural Magnetic Resonance Imaging (sMRI) volumes for the detection of two neurological disorders with cognitive impairment: Myotonic Dystrophy of type 1 (MD1) and Alzheimer Disease (AD). The feature extraction process is based on the voxel clusters detected by Voxel Based Morphometry (VBM) analysis of sMRI upon a set of patient and control subjects. This feature extraction process is specific for each kind of disease and is grounded on the findings obtained by medical experts. The 10-fold cross-validation results of several statistical and neural network based classification algorithms trained and tested on these features show high specificity and moderate sensitivity of the classifiers, suggesting that the approach is better suited for rejecting than for detecting early stages of the diseases.

## 1 Introduction

Nowadays, there is much research effort devoted to the development of ways to provide automatized diagnostic support tools that may help the clinicians

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9 to perform their work faster with additional assesment data, to meet the ever  
10 increasing demands of primary attention of a rising population of patients with  
11 neurological disorders. The present paper will be focused on the application of  
12 statistical and Computational Intelligence algorithms for the automatic detec-  
13 tion of two very specific pathologies, Alzheimer’s Disease (AD) and Myotonic  
14 Dystrophy of type 1 (MD1), from the analysis of structural (T1 weighted ) Mag-  
15 netic Resonance Imaging (sMRI) data. The AD is a primary dementia while  
16 MD1 is a muscular dystrophy, but both of them show cognitive impairment.  
17 The prevalence of MD1 in our local region of Gipuzkoa (Spain) is high[17, 18].  
18 We describe a feature extraction method based on Voxel Based Morphometry  
19 (VBM). These features will be the input for several Artificial Neural Network  
20 (ANN) and Support Vector Machine (SVM) classification systems.

21 We have found in the literature several sMRI feature extraction proposals for  
22 classification: some based on morphometric methods [16, 20, 37, 65], some based  
23 on ROIs/VOIs (regions-of-interest/volumes-of-interest) [45, 43, 24], and some  
24 on gray matter (GM) voxels in automated segmentation images [39]. There are  
25 also studies aiming to explore the improvement obtained in the SVM classifier  
26 by adding covariates such as demographic or genotype information [64]. Work  
27 has also been reported on the selection of the most informative features for  
28 classification, such as the SVM-Recursive Feature Elimination [20], the selection  
29 based on statistical tests [45, 53] or the wavelet decomposition of the RAVENS  
30 maps [43], among others.

31 Our approach uses the VBM detected clusters as a mask to select the poten-  
32 tially most discriminating voxels on the Grey Matter (GM) segmentation vol-  
33 umes. Feature vectors for classification are either the GM segmentation voxel  
34 values or some summary statistics of each cluster. We both consider the feature  
35 vector computed from all the VBM clusters and the combination of the indi-  
36 vidual classifiers built from the clusters independently. We test classification  
37 systems built using the standard SVM, with linear and non-linear (RBF) ker-  
38 nels, and some ANN architectures: Learned Vector Quantization (LVQ), Multi-  
39 Layer Perceptron (MLP), Radial Basis Function (RBF), Probabilistic Neural  
40 Networks (PNN). We have also tested combinations of SVM classifiers trained  
41 on independent VBM clusters and an Adaptive Boosting (AdaBoost) strategy  
42 tailored to the SVM [44]. As a general result, the diverse systems showed a  
43 moderate accuracy due to a moderate sensitivity, and high specificity. Best re-  
44 sults we obtained with an LVQ approach and an AdaBoost on SVM classifiers.  
45 Some of the results have been published separately in conference proceedings  
46 [25, 56, 55].

47 Section 2 gives some background medical information on the studied demen-  
48 tia. Section 3 gives a description of the subjects selected for the study, the  
49 image processing and in Section 4 we describe feature extraction details and the  
50 classifier systems. Section 5 gives classification performance results obtained in  
51 the diverse computational experiments performed on the data. Finally, section  
52 6 gives the conclusions of this work and suggestions for further research .  
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## 2 Medical background

### 2.1 Alzheimer's Disease

Alzheimer's Disease (AD) is a neurodegenerative disorder, which is one of the most common cause of dementia in old people. Due to the socioeconomic importance of the disease in occidental countries there is a strong international effort focus in AD. The diagnosis of AD can be done after the exclusion of other forms of dementia but a definitive diagnosis can only be made after a post-mortem study of the brain tissue. This is one of the reasons why Magnetic Resonance Imaging (MRI) based early diagnosis is a current research hot topic in the neurosciences. The pharmaceutical companies have already recognized that imaging techniques especially MRI and Positron Emission Tomography (PET) provide "surrogate" information concerning the pattern and rate of neurodegeneration, which can be used to monitor the effects of treatments which slow the progression of neurodegeneration. Therefore, there is high interest in the development of automated detection procedures based on MRI and other medical imaging techniques.

Besides MRI, other medical imaging methods are being studied for AD diagnosis. There are studies applying Support Vector Machine (SVM) either with linear [65, 39, 64] or nonlinear [20, 43] kernels, to discriminate AD patients from controls based on Positron Emission Tomography (PET), Single-Photon Emission Tomography (SPECT) functional volumes [24, 46, 38, 53] or studies that combine structural and functional information such as [19], where sMRI and PET volumes are used.

Many of the classification studies on the detection of AD were done with both men and women. However, it has been demonstrated that brains of women are different from men's to the extent that it is possible to discriminate the gender via MRI analysis [42]. Moreover, it has been shown that VBM is sensitive to the gender differences. For these reasons, we have been very cautious in this study. We have selected a set of 98 MRI women's brain volumes. It must be noted that this is a large number of subjects compared with the other studies referred above.

### 2.2 Myotonic Dystrophy Type 1

Myotonic Dystrophy type 1 (MD1) is a slowly progressive myopathy characterized by varying multisystemic involvement, affecting skeletal and smooth muscles, the heart (arrhythmia, electrical conductivity defects), the endocrine system (hyperinsulinemia) and eyes (cataract) [34]. It is transmitted in an autosomal dominant manner and it is due to an unstable pathological expansion of (CTG) $_n$  repeats [6]. Epidemiologically, MD1 is the most frequent neuromuscular disorder with a reported prevalence between 69 to 90 cases per million [50]. However, the prevalence is significantly higher in Gipuzkoa (North of Spain), reaching 300 cases per million inhabitants [17].

Previous neuroimaging studies using MRI of MD1 patients have found corti-

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9 cal atrophy, increased ventricular size with periventricular hypodensity, subcortical white matter involvement and calcification of the basal ganglia [12, 15, 35]. Many brain disorders have subtle morphological abnormalities of the brain not easily detected on routine examination of MR images [52]; VBM methods have become popular for detecting these abnormalities [3]. In MD1, volumetric studies have identified atrophy of the GM along different cortical areas (mainly in prefrontal area) but these previous studies are methodologically limited regarding to the sample size and the data correction level [2, 51]. Besides, these studies have analyzed the association between brain volumes and some clinical as well as genetic data, but none but none of them have measured the correlation with neuropsychological data.

## 22 3 Materials

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24 In this section we will describe the main characteristics of the sMRI data used for the computational experiments. The AD experiments were performed on a subset of the publicly available OASIS database, while the DM1 experiments were performed on a database that has been developed in the Donostia Hospital along the past years of clinical practice with this disease. The data have been obtained from diverse MRI scanners and under different imaging protocols, therefore they can not be combined at the present state of our research to produce AD versus MD1 discriminant systems.

### 34 3.1 MD1 Subjects

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36 The MD1 patients analysed in this work were selected from those attending in the outpatient consultancies at the Neurology Department of the Donostia Hospital (San Sebastian), a tertiary public hospital which covers a population of 650,000 inhabitants (almost all of Guipuzcoa province). All patients were explored by a neurologist and had previously participated in another study in which we assessed them neuropsychologically [59]. The patient-selection criteria were as follows: Inclusion criteria for MD1 patients: Between 18 and 65 years old and molecular confirmation of the clinical diagnosis. Exclusion criteria: A history of a major psychiatric or somatic disorder (in accordance with DSM-IV criteria), acquired brain damage or alcohol or drug abuse, the presence of corporal paramagnetic body devices (pacemaker, etc.) that impedes a MRI study and the presence of cerebral anomalies which could affect the volumetric analysis. An age and sex matched healthy control subject (CS) was included for each MD1 patient. This control group consisted of unaffected family members and healthy volunteers with none of these pathologies. All patients were informed of the objectives and details of the study and signed an informed consent. The study was approved by the hospital's ethics committee.

		MD1	CS
<b>Socio-demographic characteristics</b>			
Number of subjects		30	30
Age	Mean (SD)	44.0 (11.6)	44.2 (11.7)
	Min-Max	24-62	22-62
Sex n (%)	Male	14 (47%)	14 (47%)
	Female	16 (53%)	16 (53%)
Educational level n (%)	Primary	18 (60%)	5 (21%)
	Secondary	7 (23%)	9 (37%)
	Higher	5 (17%)	10 (41%)
<b>Clinical and molecular characteristics</b>			
Muscle weakness (MIRS <sup>1</sup> )	Mean (SD)	2.9 (1.2)	–
	Min-Max	1-5	
Molecular defect (CTG)	Mean (SD)	635 (472)	–
	Min-Max	65-1833	
White matter lesions n (%)	Yes	16 (53%)	5 (18%)
	No	14 (47%)	22 (82%)

Table 1: Summary of subject demographics and MD1 status. <sup>1</sup>Muscular Impairment Rating Scale.

### 3.1.1 Imaging Protocol for MD1 data

MR scanning was performed on a 1.5 Tesla scanner (Achieva Nova, Philips). The current results are based on a high-resolution volumetric “turbo field echo” (TFE) series (sagittal 3D T1 weighted acquisition, TR = 7.2, TE = 3.3, flip angle = 8, matrix = 256 x 232, slice thickness 1mm, voxel dimensions of 1mm x 1mm x 1mm, NSA = 1, n<sup>o</sup> slices 160, slice thickness= 1, gap= 0, total scan duration 5’34”). In addition to 3DT1 weighted images, conventional axial dual T2 turbo spin echo images (TR = 1800, TE = 20, flip angle = 90<sup>o</sup>, FOV= 230, matrix = 256 x 154, slice thickness= 5, gap= 1, n<sup>o</sup> acquisition =2, n<sup>o</sup> slices= 22) and fluid attenuation inversion recovery images (FLAIR) in coronal plane (TR = 10000, TI = 2800, TE= 140, FOV= 230, matrix = 256 x 159, slice thickness= 5, gap= 1, n<sup>o</sup> acquisition =2, n<sup>o</sup> slices= 25) were acquired to evaluate the presence of white matter lesions (WMLs). All the scans were acquired on the same MR scanner and no hardware or software upgrades of the equipment were carried out within the study period.

### 3.2 OASIS subjects

Ninety eight right-handed women (aged 65-96 yr) were selected from the Open Access Series of Imaging Studies (OASIS) database [48]. OASIS data set has a cross-sectional collection of 416 subjects covering the adult life span aged 18 to 96 including individuals with early-stage Alzheimer’s Disease. We have ruled out a set of 200 subjects whose demographic, clinical or derived anatomic volumes information was incomplete. For the present study there are 49 subjects

	Very mild to mild AD	CS
No. of subjects	49	49
Age	78.08 (66-96)	77.77 (65-94)
Education	2.63 (1-5)	2.87 (1-5)
Socioeconomic status	2.94 (1-5)	2.88 (1-5)
CDR (0.5 / 1 / 2)	31 / 17 / 1	0
MMSE	24 (15-30)	28.96 (26-30)

Table 2: Summary of subject demographics and dementia status. Education codes correspond to the following levels of education: 1 less than high school grad., 2: high school grad., 3: some college, 4: college grad., 5: beyond college. Categories of socioeconomic status: from 1 (biggest status) to 5 (lowest status). MMSE score ranges from 0 (worst) to 30 (best).

who have been diagnosed with very mild to mild AD and 49 non-demented. A summary of subject demographics and dementia status is shown in table 3.2.

### 3.2.1 OASIS Imaging Protocol

The OASIS database has been built following a strict imaging protocol, to avoid variations due to imaging protocol which would pose big image normalization problems. Multiple (three or four) high-resolution structural T1-weighted magnetization-prepared rapid gradient echo (MP-RAGE) images were acquired [21] on a 1.5-T Vision scanner (Siemens, Erlangen, Germany) in a single imaging session. Image parameters: TR= 9.7 msec., TE= 4.0 msec., Flip angle= 10, TI= 20 msec., TD= 200 msec., 128 sagittal 1.25 mm slices without gaps and pixels resolution of 256×256 (1×1mm).

## 4 Methods

In this section we will describe the different computational processes applied to the data. First, we summarize the Voxel Based Morphometry (VBM) process, and we give details of its independent application to the AD and MD1 data. Second, we describe the feature extraction process. Finally, we give summary descriptions of the diverse approaches used to build the classifiers, both single and combinations of classifiers.

### 4.1 Voxel-based Morphometry (VBM)

Morphometry analysis has become a common tool for computational brain anatomy studies. It allows a comprehensive measurement of structural differences within a group or across groups, not just in specific structures, but throughout the entire brain. Voxel Based Morphometry (VBM) is a computational approach to neuroanatomy that measures differences in local concentrations of brain tissue, through a voxel-wise comparison of multiple brain images

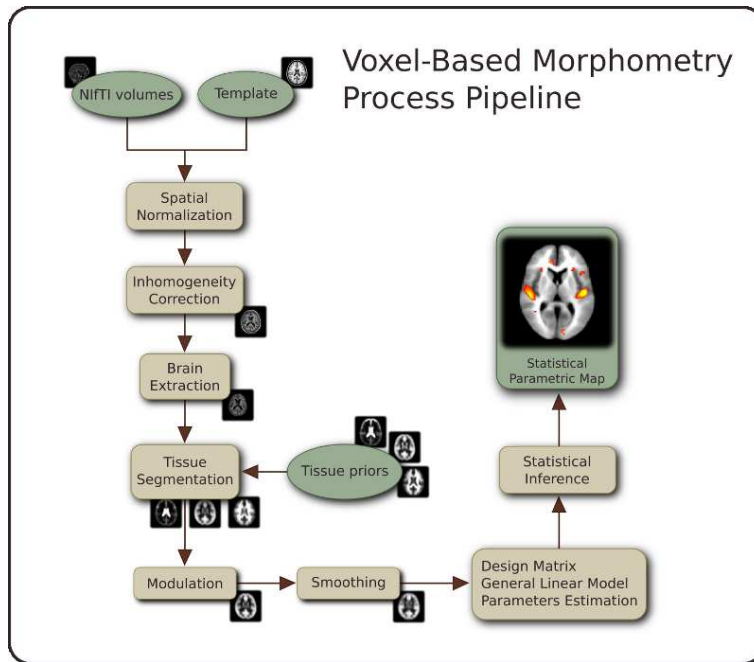


Figure 1: The processing pipeline of the Voxel Based Morphometry (VBM) on structural MRI volumes.

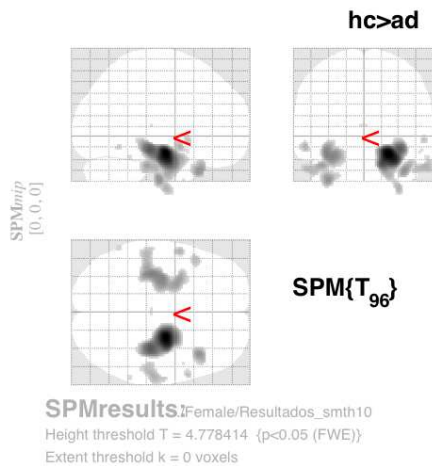
[3]. For instance, VBM has been applied to study volumetric atrophy of the grey matter (GM) in areas of neocortex of AD patients vs. control subjects [9, 57, 23]. The processing pipeline of VBM is illustrated in figure 1. The procedure involves the spatial normalization of subject images into a standard space, segmentation of tissue classes using *a priori* probability maps, smoothing to correct noise and small variations, and voxel-wise statistical tests. Smoothing is done by convolution with a Gaussian kernel whose the Full-Width at Half-Maximum (FWHM) is tuned to the data of each case study. Statistical analysis is based on the General Linear Model (GLM) to describe the data in terms of experimental and confounding effects, and residual variability, applied to each voxel independently. Statistical inference is used to test hypotheses that are expressed as linear functions of the GLM estimated regression parameters. These linear scalar functions are called contrasts in SPM terminology. The value of this contrast at each voxel constitutes a Statistical Parametric Map (SPM), which is thresholded according to the Random Field theory.

#### 4.1.1 Image processing and VBM for OASIS

We have used the average MRI volume for each subject, provided in the OASIS data set. These images are already registered and re-sampled into a 1-mm isotropic image in atlas space and the bias field has been already corrected [48].



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 9 The Statistical Parametric Mapping software (SPM8) [1] was used to compute  
 10 the VBM which gives us the spatial mask to obtain the classification features.  
 11 Images were reoriented into a right-handed coordinate system to work with  
 12 SPM8. The tissue segmentation step does not need to perform bias correction.  
 13 We performed the modulation normalization for GM, because we are interested  
 14 in this tissue for this study. We performed a spatial smoothing before perform-  
 15 ing the voxel-wise statistics, setting the FWHM of the Gaussian kernel to 10mm  
 16 isotropic. A GM mask was created from the average of the GM segmentation  
 17 volumes of the subjects under study. Thresholding the average GM segmenta-  
 18 tion, we obtain a binary mask that includes all voxels with probability greater  
 19 than 0.1 in the average GM segmentation volume. This interpretation is not  
 20 completely true, since the data is modulated, but it is close enough for the  
 21 mask to be reasonable. We designed the statistical analysis as a two-sample  
 22 t-test in which the first group corresponds with AD subjects. In SPM software  
 23 jargon: the contrast has been set to [-1 1], a right-tailed (groupN > groupAD),  
 24 correction FWE, p-value=0.05. The VBM detected clusters are used for the  
 25 feature extraction for the classification procedures. Statistical significance  
 26 was determined using an extent threshold of 0 adjacent voxels for two sample  
 27 comparisons. The clusters of significant voxels detected by the VBM analysis  
 28 are displayed in figure 2, they agree with the findings reported in the literature  
 29 [9, 57, 23].  
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 48 Figure 2: SPM results: clusters of significant voxels with increased gray matter  
 49 density in the controls relative to the patient subjects, detected by the VBM  
 50 process.  
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#### 4.1.2 Image processing and VBM for MD1

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 55 The Statistical Parametric Mapping software (SPM8) [1] was used to compute  
 56 the VBM which gives us the spatial mask to obtain the classification features.  
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9 Images were reoriented into a right-handed coordinate system to work with  
10 SPM8. The tissue segmentation step does not need to perform bias correction.  
11 We performed the modulation normalization for GM, because we are interested  
12 in this tissue for this study. We performed a spatial smoothing before perform-  
13 ing the voxel-wise statistics, setting the FWHM of the isotropic Gaussian kernel  
14 to 8mm, 9mm, 10mm, 11mm and 12mm . For all comparisons we have applied  
15 a significance probability threshold of  $p < 0.05$  FWE corrected for multiple com-  
16 parisons at a voxel-level. Statistical significance was determined using spatial  
17 extent thresholds of 0, 100 and 200 adjacent voxels for two sample comparisons.  
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## 20 4.2 Feature extraction

21 We have tested two different feature vector extraction processes, based on the  
22 voxel location clusters detected as a result of the VBM analysis. The process  
23 is illustrated in figure 3. The VBM detected clusters are used as masks to  
24 determine the voxel positions where the features are extracted. These masks  
25 are applied to the GM density volumes result of the segmentation step in the  
26 VBM analysis.  
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- 28 1. The first feature extraction process computes the mean and standard de-  
29 viation of the GM voxel values of each voxel location cluster, we denote  
30 these features as MSD in the result tables given below.  
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- 32 2. The second feature extraction process computes a very high dimensional  
33 vector with all the GM segmentation values for the voxel locations included  
34 in each VBM detected cluster. The voxel values were ordered in this  
35 feature vector according to the coordinate lexicographical ordering. We  
36 denote these features as VV in the result tables below.  
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## 39 4.3 Neural Network and Statistical Classification Algo- 40 rithms

41 We deal with two class classification problems, given a collection of train-  
42 ing/testing input feature vectors  $X = \{\mathbf{x}_i \in \mathbb{R}^n, i = 1, \dots, l\}$  and the corre-  
43 sponding labels  $\{y_i \in \{-1, 1\}, i = 1, \dots, l\}$ , which sometimes can be better de-  
44 noted in aggregated form as a binary vector  $\mathbf{y} \in \{-1, 1\}^l$ . The algorithms  
45 described below build some classifier systems based on this data. The simplest  
46 algorithm is the 1-NN which involves no adaptation and uses all the training  
47 data samples. The classification rule is of the form:  
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$$50 c(\mathbf{x}) = y_{i^*} \text{ where } i^* = \arg \min_{i=1, \dots, l} \{\|\mathbf{x} - \mathbf{x}_i\|\},$$

51 that is, the assigned class is that of the closest training vector. To validate their  
52 generalization power we use ten fold cross-validation.  
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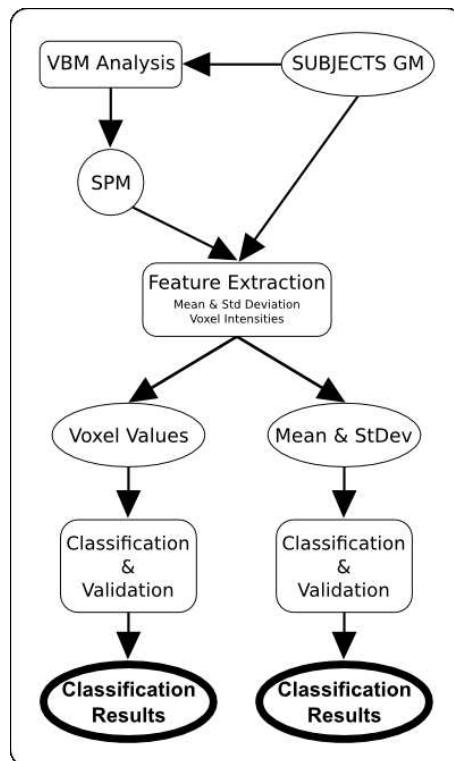


Figure 3: Flow diagram of the feature extraction process from the subjects' GM segmentation volumes.

### 4.3.1 Support Vector Machines

The Support Vector Machines (SVMs) have attracted attention from the pattern recognition community [24, 62] owing to a number of theoretical and computational merits derived from [63]. SVM separates a given set of binary labelled training data with a hyperplane that is maximally distant from the two classes (known as the maximal margin hyperplane). The objective is to build a discriminating function using training data that will correctly classify new examples  $(\mathbf{x}, y)$ . When no linear separation of the training data is possible, SVMs can work effectively in combination with kernel techniques using the kernel trick, so that the hyperplane defining the SVMs corresponds to a nonlinear decision boundary in the input space that is mapped to a linearised higher-dimensional space [63]. In this way the decision function can be expressed in terms of the support vectors only:

$$f(\mathbf{x}) = \text{sign} \left( \sum \alpha_i y_i K(\mathbf{s}_i, \mathbf{x}) + w_0 \right)$$

where  $K(.,.)$  is a kernel function,  $\alpha_i$  is a weight constant derived from the SVM process and the  $\mathbf{s}_i$  are the support vectors [63].

The Support Vector Machine (SVM)[63] algorithm used for this study is included in the libSVM (<http://www.csie.ntu.edu.tw/~cjlin/libsvm/>) software package. The implementation is described in detail in [13]. Given training vectors  $\mathbf{x}_i \in \mathbb{R}^n, i = 1, \dots, l$  of the subject features of the two classes, and a vector  $\mathbf{y} \in \mathbb{R}^l$  such that  $y_i \in \{-1, 1\}$  labels each subject with its class, in our case, for example, patients were labeled as -1 and control subject as 1. To construct a classifier, the SVM algorithm tries to maximize the classification margin. To this end it solves the following optimization problem:

$$\min_{w, b, \xi} \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^l \xi_i$$

subject to  $y_i(\mathbf{w}^T \phi(\mathbf{x}_i) + b) \geq (1 - \xi_i), \xi_i \geq 0, i = 1, 2, \dots, n$ . The dual optimization problem is

$$\min_{\alpha} \frac{1}{2} \boldsymbol{\alpha}^T \mathbf{Q} \boldsymbol{\alpha} - \mathbf{e}^T \boldsymbol{\alpha},$$

subject to  $\mathbf{y}^T \boldsymbol{\alpha} = 0, 0 \leq \alpha_i \leq C, i = 1, \dots, l$ , where  $\mathbf{e}$  is the vector of all ones,  $C > 0$  is the upper bound on the error,  $\mathbf{Q}$  is an  $l \times l$  positive semi-definite matrix,  $Q_{ij} \equiv y_i y_j K(\mathbf{x}_i, \mathbf{x}_j)$ , and  $K(\mathbf{x}_i, \mathbf{x}_j) \equiv \phi(\mathbf{x}_i)^T \phi(\mathbf{x}_j)$  is the kernel function that describes the behavior of the support vectors. Here, the training vectors  $\mathbf{x}_i$  are mapped into a higher (maybe infinite) dimensional space by the function  $\phi(\mathbf{x}_i)$ .  $C$  is a regularization parameter used to balance the model complexity and the training error.

The kernel function chosen results in different kinds of SVM with different performance levels, and the choice of the appropriate kernel for a specific application is a difficult task. In this study two different kernels were tested: the

linear and the radial basis function (RBF) kernel. The linear kernel function is defined as  $K(\mathbf{x}_i, \mathbf{x}_j) = 1 + \mathbf{x}_i^T \mathbf{x}_j$ , this kernel shows good performance for linearly separable data. The RBF kernel is defined as  $K(\mathbf{x}_i, \mathbf{x}_j) = \exp(-\frac{\|\mathbf{x}_i - \mathbf{x}_j\|^2}{2\sigma^2})$ . This kernel is best suited to deal with data that have a class-conditional probability distribution function approaching the Gaussian distribution [8]. The RBF kernel is largely used in the literature because it corresponds to the mapping into an infinite dimension feature space, and it can be tuned by its variance parameter  $\sigma$ .

### 4.3.2 Multi Layer Perceptron trained with Backpropagation

Backward propagation of errors, or backpropagation (BP), [54, 36, 33] is a non-linear generalization of the squared error gradient descent learning rule for updating the weights of artificial neurons in a single-layer perceptron, generalized to feed-forward networks, also called Multi-Layer Perceptron (MLP). Backpropagation requires that the activation function used by the artificial neurons (or "nodes") is differentiable with its derivative being a simple function of itself. The backpropagation of the error allows to compute the gradient of the error function relative to the hidden units. It is analytically derived using the chain rule of calculus. During on-line learning, the weights of the network are updated at each input data item presentation. We have used the resilient backpropagation, which uses only the derivative sign to perform the weight updating.

We restrict our presentation of BP to train the weights of the MLP for the current two class problem. Let the instantaneous error  $E_p$  be defined as:

$$E_p(\mathbf{w}) = \frac{1}{2} (y_p - z_K(\mathbf{x}_p))^2, \quad (1)$$

where  $y_p$  is the  $p$ -th desired output  $y_p$ , and  $z_K(x_p)$  is the network output when the  $p$ -th training exemplar  $x_p$  is inputted to the MLP composed of  $K$  layers, whose weights are aggregated in the vector  $\mathbf{w}$ . The output of the  $j$ -th node in layer  $k$  is given by:

$$z_{k,j}(\mathbf{x}_p) = f \left( \sum_{i=0}^{N_{k-1}} w_{k,j,i} z_{k-1,i}(\mathbf{x}_p) \right), \quad (2)$$

where  $z_{k,j}$  is the output of node  $j$  in layer  $k$ ,  $N_k$  is the number of nodes in layer  $k$ ,  $w_{k,j,i}$  is the weight which connects the  $i$ -th node in layer  $k-1$  to the  $j$ -th node in layer  $k$ , and  $f(\cdot)$  is the sigmoid nonlinear function, which has a simple derivative:

$$f'(\alpha) = \frac{df(\alpha)}{d\alpha} = f(\alpha)(1 - f(\alpha)). \quad (3)$$

The convention is that  $z_{0,j}(\mathbf{x}_p) = \mathbf{x}_{p,j}$ . Let the total error  $E_T$  be defined as follows:

$$E_T(\mathbf{w}) = \sum_{p=1}^l E_p(\mathbf{w}), \quad (4)$$

where  $l$  is the cardinality of  $X$ . Note that  $E_T$  is a function of both the training set and the weights in the network. The backpropagation learning rule is defined as follows:

$$\Delta w(t) = -\eta \frac{\partial E_p(\mathbf{w})}{\partial w} + \alpha \Delta w(t-1), \quad (5)$$

where  $0 < \eta < 1$ , which is the learning rate, the momentum factor  $\alpha$  is also a small positive number, and  $w$  represents any single weight in the network. In the above equation,  $\Delta w(t)$  is the change in the weight computed at time  $t$ . The momentum term is sometimes used ( $\alpha \neq 0$ ) to improve the smooth convergence of the algorithm. The algorithm defined by equation (5) is often termed as *instantaneous backpropagation* because it computes the gradient based on a single training vector. Another variation is *batch backpropagation*, which computes the weight update using the gradient based on the total error  $E_T$ .

To implement this algorithm we must give an expression for the partial derivative of  $E_p$  with respect to each weight in the network. For an arbitrary weight in layer  $k$  this can be written using the Chain Rule:

$$\frac{\partial E_p(\mathbf{w})}{\partial w_{k,j,j}} = \frac{\partial E_p(\mathbf{w})}{\partial z_{k,j}(\mathbf{x}_p)} \frac{\partial z_{k,j}(\mathbf{x}_p)}{\partial w_{k,j,i}}. \quad (6)$$

Because the derivative of the activation function follows equation 3, we get:

$$\frac{\partial z_{k,j}(\mathbf{x}_p)}{\partial w_{k,j,i}} = z_{k,j}(\mathbf{x}_p) (1 - z_{k,j}(\mathbf{x}_p)) z_{k-1,j}(\mathbf{x}_p), \quad (7)$$

and

$$\frac{\partial E_p(\mathbf{w})}{\partial z_{k,j}(\mathbf{x}_p)} = \sum_{m=1}^{N_{k+1}} \frac{\partial E_p(\mathbf{w})}{\partial z_{k+1,m}(\mathbf{x}_p)} z_{k+1,m}(\mathbf{x}_p) (1 - z_{k+1,m}(\mathbf{x}_p)) w_{k+1,m,j},$$

which at the output layer corresponds to the output error :

$$\frac{\partial E_p(\mathbf{w})}{\partial z_K(\mathbf{x}_p)} = z_L(\mathbf{x}_p) - y_p. \quad (8)$$

### 4.3.3 Radial Basis Function Networks

Radial Basis Function networks (RBF) [14, 36] are a type of ANN that use radial basis functions as activation functions. RBFs consist of a two layer neural network, where each hidden unit implements a radial activated function. The output units compute a weighted sum of hidden unit outputs. Training consists of the unsupervised training of the hidden units followed by the supervised training of the output units' weights. RBFs have their origin in the solution of

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a multivariate interpolation problem [7]. Arbitrary function  $g(\mathbf{x}) : \mathbb{R}^n \rightarrow \mathbb{R}$  can be approximated by a map defined by a RBF network with a single hidden layer of  $K$  units:

$$\hat{g}_{\boldsymbol{\theta}}(\mathbf{x}) = \sum_{j=1}^K w_j \phi(\sigma_j, \|\mathbf{x} - \mathbf{c}_j\|), \quad (9)$$

where  $\boldsymbol{\theta}$  is the vector of RBF parameters including  $w_j, \sigma_j \in \mathbb{R}$ , and  $\mathbf{c}_j \in \mathbb{R}^n$ ; let us denote  $\mathbf{w} = (w_1, w_2, \dots, w_p)^T$ , then the vector of RBF parameters can be expressed as  $\boldsymbol{\theta}^T = (\mathbf{w}^T, \sigma_1, \mathbf{c}_1^T, \dots, \sigma_K, \mathbf{c}_K^T)$ . Each RBF is defined by its center  $\mathbf{c}_j \in \mathbb{R}^n$  and width  $\sigma_j \in \mathbb{R}$ , and the contribution of each RBF to the network output is weighted by  $w_j$ . The RBF function  $\phi(\cdot)$  is a nonlinear function that monotonically decreases as  $\mathbf{x}$  moves away from its center  $\mathbf{c}_j$ . The most common RBF used is the isotropic Gaussian:

$$\hat{g}_{\boldsymbol{\theta}}(\mathbf{x}) = \sum_{j=1}^p w_j \exp\left(-\frac{\|\mathbf{x} - \mathbf{c}_j\|^2}{2\sigma_j^2}\right).$$

The network can be thought as the composition of two functions  $\hat{g}_{\boldsymbol{\theta}}(\mathbf{x}) = W \circ \Phi(\mathbf{x})$ , the first one implemented by the RBF units  $\Phi : \mathbb{R}^n \rightarrow \mathbb{R}^K$  performs a data space transformation which can be a dimensionality reduction or not, depending on whether  $K > n$ . The second function corresponds to a single layer linear Perceptron  $W : \mathbb{R}^K \rightarrow \mathbb{R}$  giving the map of the RBF transformed data into the class labels. Training is accordingly decomposed into two phases. First a clustering algorithm is used to estimate the Gaussian RBF parameters (centres and variances). Afterwards, linear supervised training is used to estimate the weights from the hidden RBF to the output. In order to obtain a binary class label output, a hard limiter function is applied to the continuous output of the RBF network.

#### 4.3.4 Probabilistic Neural Networks

A Probabilistic Neural Network (PNN) [61] uses a kernel-based approximation to form an estimate of the probability density function of categories in a classification problem. In fact, it is a generalization of the Parzen windows distribution estimation, and a filtered version of the 1-NN classifier. The distance of the input feature vector  $\mathbf{x}$  to the stored patterns is filtered by a RBF function. Let us denote the data sample partition as  $X = X_1 \cup X_{-1}$ , where  $X_1 = \{\mathbf{x}_1^1, \dots, \mathbf{x}_{n_1}^1\}$  and  $X_{-1} = \{\mathbf{x}_1^{-1}, \dots, \mathbf{x}_{n_{-1}}^{-1}\}$ . That is, superscripts denote the class of the feature vector and  $n_1 + n_{-1} = n$ . Each pattern  $\mathbf{x}_j^i$  of training data sample is interpreted as the weight of the  $j$ -th neuron of the  $i$ -th class. Therefore the response of the neuron is computed as the probability of the input feature vector according to a Normal distribution centered at the stored pattern:

$$\Phi_{i,j}(\mathbf{x}) = \frac{1}{(2\pi)^{n/2} \sigma^n} \exp\left[-\frac{\|\mathbf{x} - \mathbf{x}_j^i\|^2}{2\sigma^2}\right], \quad (10)$$

Therefore the output of the neuron is inside  $[0, 1]$ . The tuning of a PNN network depends on selecting the optimal sigma value of the spread  $\sigma$  of the RBF functions, which can be different for each class. In this paper an exhaustive search for the optimal spread value in the range  $(0, 1)$  for each training set has been done. The output of the PNN is an estimation of the likelihood of the input pattern  $\mathbf{x}$  being from class  $i \in \{-1, 1\}$  by averaging the output of all neurons that belong to the same class:

$$p_i(x) = \frac{1}{n_i} \sum_{j=1}^{n_i} \Phi_{i,j}(\mathbf{x}). \quad (11)$$

The decision rule based on the output of all the output layer neurons is simply:

$$\hat{y}(\mathbf{x}) = \arg \max_i \{p_i(\mathbf{x})\}, \quad i \in \{-1, 1\}. \quad (12)$$

where  $\hat{y}(\mathbf{x})$  denotes the estimated class of the pattern  $\mathbf{x}$ . If the a priori probabilities for each class are the same, and the losses associated with making an incorrect decision for each class are the same, the decision layer unit classifies the pattern  $\mathbf{x}$  in accordance with the optimal Bayes' rule.

#### 4.3.5 Learning Vector Quantization

Learning vector quantization (LVQ) [40, 60] Learning Vector Quantization (LVQ) as introduced by Kohonen [41] represents every class  $c \in \{-1, 1\}$  by a set  $W(c) = \{\mathbf{w}_i \in \mathbb{R}^n; i = 1, \dots, N_c\}$  of weight vectors (prototypes) which tessellate the input feature space. Let us denote  $W$  the union of all prototypes, regardless of class. If we denote  $c_i$  the class the weight vector  $\mathbf{w}_i \in W$  is associated with, the decision rule that classifies a feature vector  $\mathbf{x}$  is as follows:

$$c(\mathbf{x}) = c_{i^*}$$

where

$$i^* = \arg \min_i \{\|\mathbf{x} - \mathbf{w}_i\|\}.$$

The training algorithm of LVQ aims at minimizing the classification error on the given training set, i.e.,  $E = \sum_j (y_j - c(\mathbf{x}_j))^2$ , modifying the weight vectors on the presentation of input feature vectors. The heuristic weight updating rule is as follows:

$$\Delta \mathbf{w}_{i^*} = \begin{cases} \epsilon \cdot (\mathbf{x}_j - \mathbf{w}_{i^*}) & \text{if } c_{i^*} = y_j \\ -\epsilon \cdot (\mathbf{x}_j - \mathbf{w}_{i^*}) & \text{otherwise} \end{cases}, \quad (13)$$

that is, the input's closest weight is adapted either toward the input if their classes match, or away from it if not. This rule is highly unstable, therefore, the practical approach consists in performing an initial clustering of each class data samples to obtain an initial weight configuration using equation 13 to perform the fine tuning of the classification boundaries. This equation corresponds to



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9 a LVQ1 approach. The LVQ2 approach involves determining the two input  
10 vector's closest weights. They are moved toward or away the input according  
11 to the matching of their classes.  
12

### 13 **4.3.6 Combination of independent SVMs trained per VBM cluster**

14 We have considered also the construction of independent SVM classifiers for  
15 each VBM detected cluster, meaning that only the corresponding features are  
16 used for train/test, and the combination of their responses in two ways:  
17

- 18 1. By a simple majority voting, using the cluster with greatest statistical  
19 significance to resolve ties. This can be viewed as a simplified combination  
20 of classifiers. We denote this system Indep-SVM in the results reported  
21 below.  
22
- 23 2. We have defined a combination of classifiers weighted by the individual  
24 training errors, where the classifier weights are computed using the Ad-  
25 aBoost SVM algorithm [44], assuming an uniform weighting of the data  
26 samples. We present this approach in Algorithm 1. We denote AB-SVM  
27 this approach in the tables below.  
28  
29

### 30 **4.3.7 Adaptive Boosting**

31 Adaptive Boosting (AdaBoost)[58, 22] is a meta-algorithm for machine learning  
32 that can be used in conjunction with many other learning algorithms to improve  
33 their performance. AdaBoost is adaptive in the sense that subsequent classifiers  
34 built are tweaked in favor of those instances misclassified by previous classifiers.  
35 AdaBoost is sensitive to noisy data and outliers. Otherwise, it is less susceptible  
36 to the over-fitting problem than most learning algorithms.  
37

38 AdaBoost calls a weak classifier repeatedly in a series of rounds  $t = 1, \dots, T$ .  
39 For each call a distribution of weights  $W_t$  is updated and indicates the impor-  
40 tance of examples in the data set for the classification. On each round, the  
41 weights of each incorrectly classified example are increased (or alternatively,  
42 the weights of each correctly classified example are decreased), so that the new  
43 classifier focuses more on those examples.  
44

45 Following these ideas, we have also tested a combination of SVM classifiers  
46 following the the Diverse-AdaBoost-SVM [44], shown here as Algorithm 2. In  
47 this approach we built a sequence of SVM classifiers of increasing variance pa-  
48 rameter. The results of the classifiers are weighted according to their statistical  
49 error to obtain the response to the test inputs in the 10-fold validation process.  
50 We denote DAB-SVM this approach in the tables below.  
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## 53 **5 Computational Experiments Results**

54 We evaluate the performance of the classifiers built with the diverse strategy  
55 using a 10-fold cross-validation methodology, illustrated in figure 4. We have  
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**Algorithm 1** Combining the independent SVM trained per cluster

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1. **Input:** as many sets of training samples with labels as clusters in the statistical parametric map  $T_k = \{(x_1, y_1), \dots, (x_N, y_N)\}, k = 1..C$ , where  $N$  is the number of samples of each cluster.
2. **Initialize:** the weights of training samples:  $w_i^k = 1/N$ , for all  $i = 1, \dots, N$
3. **For each  $k$  cluster do**
  - (a) Search the best  $\gamma$  for the RBF kernel for the training set  $T_k$ , we denote it as  $\gamma_k$ .
  - (b) Train the SVM with  $T_k$  and  $\gamma_k$ , we denote the classifier as  $h_k$ .
  - (c) Classify the same training  $T_k$  set with  $h_k$ .
  - (d) Calculate the training error of  $h_k$ :  $\epsilon_k = \sum_{i=1}^N w_i^k, y_i \neq h_k(x_i)$ .
  - (e) Compute the weight of the cluster classifier  $h_k$ :  $\alpha_k = \frac{1}{2} \ln(\frac{\epsilon_k}{1-\epsilon_k})$ .
4. **Output:** for each test data  $x$  its classification is  $f(x) = \text{sign}(\sum_{k=1}^C \alpha_k h_k(x))$ .

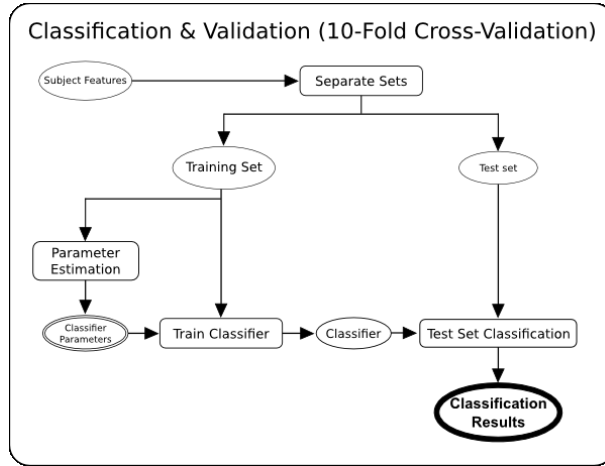


Figure 4: Flow chart of the 10-fold cross validation procedure followed in the experiments reported in this paper.

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**Algorithm 2** Diverse AdaBoostSVM

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1. **Input:** a set of training samples with labels  $\{(x_1, y_1), \dots, (x_N, y_N)\}$ ; the initial  $\sigma$ ,  $\sigma_{ini}$ ; the minimal  $\sigma$ ,  $\sigma_{min}$ ; the step of  $\sigma$ ,  $\sigma_{step}$ ; the threshold on diversity  $DIV$ .
  2. **Initialize:** the weights of training samples:  $w_i^t = 1/N$ , for all  $i = 1, \dots, N$
  3. **Do while** ( $\sigma > \sigma_{ini}$ )
    - (a) Calculate gamma:  $\gamma = (2\sigma^2)^{-1}$ .
    - (b) Use  $\sigma$  to train a component classifier  $h_t$  on the weighted training set.
    - (c) Calculate the training error of  $h_t$ :  $\epsilon_t = \sum_{i=1}^N w_i^t, \quad y_i \neq h_t(x_i)$ .
    - (d) Calculate the diversity of  $h_t$ :  $D_t = \sum_{i=1}^N d_t(x_i)$ , where  $d_t(x_i) = \begin{cases} 0 & \text{if } h_t(x_i) = y_i \\ 1 & \text{if } h_t(x_i) \neq y_i \end{cases}$
    - (e) Calculate the diversity of weighted component classifiers and the current classifier:  $D = \sum_{t=1}^T \sum_{i=1}^N d_t(x_i)$ .
    - (f) If  $\epsilon_t > 0.5$  or  $D < DIV$ : decrease  $\sigma$  by  $\sigma_{step}$  and go to (a).
    - (g) Set weight of the component classifier  $h_t$ :  $\alpha_t = \frac{1}{2} \ln(\frac{\epsilon_t}{1-\epsilon_t})$ .
    - (h) Update the weights of training samples:  $w_i^{t+1} = w_i^t \exp(-\alpha y_i h_t(x_i))$ .
    - (i) Normalize the weights of training samples:  $w_i^{t+1} = w_i^{t+1} (\sum_{i=1}^N w_i^{t+1})^{-1}$ .
  4. **Output:**  $f(x) = \text{sign}(\sum_{k=1}^C \alpha_k h_k(x))$ .
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 9 encoded the classes as follows: 0 for patients, 1 for controls. Positives corre-  
 10 spond to class 0. To quantify the results we measured the Accuracy defined as  
 11 the ratio of the number of test volumes correctly classified to the total of tested  
 12 volumes. We also quantified the sensitivity and specificity of each test defined  
 13 as  $Sensitivity = \frac{TP}{TP+FN}$  and  $Specificity = \frac{TN}{TN+FP}$ , where true positives (TP)  
 14 is the number of patient volumes correctly classified; true negatives (TN) is the  
 15 number of control volumes correctly classified; false positives (FP) is the num-  
 16 ber of control volumes classified as diseased patients and false negatives (FN)  
 17 is the number of diseased patient volumes classified as control subjects. As the  
 18 image assessment is an additional finding meant to support other diagnostic  
 19 information sources, there is a specific need for high sensitivity and specificity  
 20 systems. Thus, these performance measure were preferred above others, like  
 21 the F-measure or the Area under ROC, which are better suited to explore and  
 22 discuss the parameter sensitivity of the classification building algorithm [47].  
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## 25 5.1 Results on AD detection on the OASIS data

26 We report the average accuracy, sensitivity and specificity of the 10-fold cross-  
 27 validation of the systems developed for AD detection computed over the OASIS  
 28 data. For all the classifiers, we have determined the optimal values of the  
 29 classifier parameters via independent grid searches performed at each cross-  
 30 validation fold. For the SVM we searched for the optimal  $C$  and  $\gamma$  values. For  
 31 the MLP-BP we look for the optimal number of hidden units. For the RBF and  
 32 PNN, the spread of the radial basis functions was determined. For the LVQ  
 33 the number of hidden units was determined. For the Diverse AdaBoost SVM  
 34 (DAB-SVM) the parameters of the AdaBoost were set as follows:  $\sigma_{min} = 0.1$ ,  
 35  $\sigma_{ini} = 100$ ,  $\sigma_{step} = 0.1$ . The DIV value is set as as 0.6.  
 36

37 The results on the MSD features (24 values from each volume) are presented  
 38 in table 3. The best accuracy results were obtained by the non linear SVM  
 39 with RBF kernels, specially when embedded in the AdaBoost process (0.85).  
 40 The LVQ approach give almost comparable results. Overall, it must be noted  
 41 that the specificity is systematically higher than the sensitivity for all the clas-  
 42 sification strategies tested. Detailed examination of the results reveals that the  
 43 decrease of sensitivity is due to the bad recognition results on the AD subjects  
 44 at early stages of the disease. As the trend is common to all the classification al-  
 45 gorithms tested, this lack of sensitivity must be attributed to the feature vector  
 46 computed from the VBM detected clusters.  
 47

48 The average results of 10-fold cross-validation tests computed on the VV  
 49 features, are presented in table 4. For this definition of the feature vector,  
 50 the number of features is 3611. Again the specificity is systematically greater  
 51 than the classifier’s sensitivity at all cases, suggesting that the feature vector  
 52 definition must be improved to cope with the early detection cases. We obtain  
 53 a best accuracy result with the AdaBoost applied to the SVM with RBF kernel  
 54 trained independently at each VBM detected cluster (rbf-AB-SVM). Despite  
 55 this result, which is the best accuracy found, the remaining classifier results are  
 56 significantly worse for the VV features than for the MSD features. This must  
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 58

Classif.	Accuracy	Sensitivity	Specificity
linear SVM	0.78	0.72	0.88
rbf SVM	<b>0.81</b>	0.75	0.89
MLP-BP	0.78	0.69	0.88
RBF	0.66	0.65	0.68
PNN	0.78	0.62	0.94
LVQ1	<b>0.81</b>	0.72	0.90
LVQ2	<b>0.83</b>	0.74	0.92
Indep-linear-SVM	0.74	0.51	0.97
Indep-rbf-SVM	0.75	0.56	0.95
linear-AB-SVM	0.71	0.54	0.88
rbf-AB-SVM	0.79	0.78	0.80
rbf-DAB-SVM	<b>0.85</b>	0.78	0.92

Table 3: Results over the MSD features computed from the OASIS data for AD detection

be accounted to fact that the VV dimensionality is several orders of magnitude greater than the MSD and the proposed classifiers are unable to deal with that and the the consequent data scarcity. Note that the best result in table 4 corresponds to the independent training of SVM for each detected cluster. This “divide and conquer” strategy seems to produce good results in this case.

## 5.2 MD1 Results

In the computational experiments done on the MD1 data, we focus on the SVM classifier and explore the effect of the various VBM parameters on the resulting classification accuracy, sensitivity and specificity. In the tables below we show results for various FWHM and spatial cluster extent threshold (Size-Thr) value settings in the SPM processing to obtain the VBM clusters of pixels with significant differences. Note that the increase in the FWHM parameter naturally implies an increase in the number of features considered. The increase of the Size-Thr parameter implies that more clusters are rejected because of their small size, and the resulting feature vector has lower dimensionality. The results on the MSD features are presented in table 5, while the results on the VV features are presented in table 6. Note that there are few instances that reach the 80% accuracy. Notice also in both tables that the specificity is systematically greater than the sensitivity. As was said in the AD study above, this trend forces to attribute the lack of sensitivity to the feature extraction process. In order to deal with the milder dementia cases, the process must be improved. It must be also taken into account that until now there have not been findings in sMRI associated with the MD1, meaning that the works reported here are the among the first published results in this sense. Another interesting effect that can be appreciated in the tables 5 and 6 is that growing number of features, obtained with stronger smoothing does not imply growing classification

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Classif.	Accuracy	Sensitivity	Specificity
linear SVM	0.73	0.72	0.75
rbf SVM	0.76	0.77	0.76
MLP-BP	0.78	0.72	0.84
RBF	0.72	0.65	0.80
PNN	0.74	0.68	0.81
LVQ1	0.79	0.76	0.82
LVQ2	0.77	0.76	0.78
Indep-linear-SVM	0.77	0.74	0.80
Indep-rbf-SVM	0.78	0.76	0.82
linear-AB-SVM	0.73	0.76	0.70
rbf-AB-SVM	<b>0.86</b>	0.80	0.92
rbf-DAB-SVM	0.78	0.71	0.85

Table 4: Results over the VV features computed from the OASIS data for AD detection

accuracy. This goes contrary to the assessments by human experts that favor stronger smoothing in order to obtain better and bigger detections of the effect.

### 5.3 Discussion of results.

The classifiers applied to the data features make decisions based on the whole of the feature vector. However, the locations of the feature sources, the voxel cluster found by VBM, has some clinical interpretations. For AD the voxel cluster findings were mostly located in the temporal lobe, though some voxels in the frontal lobe have also been detected. These results confirm previous findings of temporal lobe atrophic changes in AD [4, 11, 10] [...], and suggest that these abnormalities may be confined to specific sites within that lobe, rather than showing a widespread distribution. The classification results are a second level assessment of these findings, because they show that it is possible some degree of AD prediction from them.

For MD1 the most discriminant voxels were in the caudate nucleus, fronto-parietal lobe and thalamus. These results involving the fronto-parietal areas, agree with previous studies [2] and with the profile suggested by our previous neuropsychological results in a large DM1 sample [59]. In fact, we have found the volume corresponding to the caudate nuclei and the thalamus to be smaller in DM1 patients than in the CS. Basal ganglia have traditionally been associated with motor processes, although there is increasing evidence to support their role in cognitive functions [49]. Basal ganglia nuclei relate to one another and to the cortex through different cortico-striatal loops, which emphasizes the functional interrelationship between the neocortex, the striatum and the thalamus. Three of the five loops in which the striatum is involved pass through the caudate and the thalamus on the way to the cortex: the oculomotor, dorsolateral prefrontal and lateral orbitalfrontal loops [31]. The

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FWHM(mm)	Size-Thr	#Features	Accuracy	Sensitivity	Specificity
8	0	76	0.78	0.73	0.83
	100	8	0.77	0.67	0.87
	200	4	0.77	0.67	0.87
9	0	76	<b>0.80</b>	0.70	0.90
	100	16	0.75	0.67	0.83
	200	4	0.76	0.67	0.87
10	0	70	0.78	0.63	0.93
	100	22	0.77	0.73	0.80
	200	8	0.78	0.70	0.87
11	0	64	0.72	0.63	0.80
	100	24	0.75	0.63	0.87
	200	12	0.75	0.63	0.87
12	0	68	0.72	0.63	0.80
	100	36	0.73	0.63	0.83
	200	18	0.75	0.70	0.80

Table 5: SVM classification results (10-fold crossvalidation) for MSD features, based on t-test VBM of the data, FWE=0.05

FWHM	Threshold	Features	Accuracy	Sensitivity	Specificity
8	0	2059	<b>0.82</b>	0.83	0.80
	100	1226	0.78	0.70	0.87
	200	958	<b>0.80</b>	0.80	0.77
9	0	2826	0.78	0.73	0.83
	100	2044	0.77	0.73	0.80
	200	1182	0.75	0.67	0.83
10	0	3710	0.77	0.73	0.80
	100	3103	<b>0.80</b>	0.77	83
	200	2131	0.73	0.70	0.77
11	0	5022	0.73	0.73	0.73
	100	4278	0.78	0.73	0.83
	200	3434	0.75	0.70	0.80
12	0	6542	0.76	0.73	0.80
	100	6391	0.75	0.70	0.80
	200	5148	0.73	0.70	0.76

Table 6: SVM classification results (10-fold crossvalidation) for VV features, based on t-test VBM of the data, FWE=0.05



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9 last two target two prefrontal cortical areas that are thought to be involved  
10 in various aspects of cognitive behaviour. In fact, the dorsolateral cortex is  
11 the structure mostly closely associated with executive functions and allows the  
12 organization of information to facilitate a response. The orbitofrontal circuit  
13 allows the integration of limbic and emotional information with behavioural  
14 responses [5].  
15

## 16 6 Conclusions

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19 In this work we have studied several supervised classification systems applied to  
20 discriminate patients with neurocognitive disorders (AD and MD1) from control  
21 subjects based on structural MRI (T1-weighted) data. The feature extraction  
22 processes is based on the voxel clusters detected by a VBM analysis. For the  
23 discrimination between AD patients and controls we achieve the construction of  
24 classifiers with an accuracy of 0.86 in the best case shown in table 4 in the case  
25 of OASIS females and 0.82 in case of MD1 subjects. A result of 86% of accuracy  
26 is really encouraging considering the number of subjects in the database and all  
27 the biases and errors involved in the registration, segmentation and smoothing  
28 processes performed in the pre-processing steps of the volumes in the VBM.  
29 After close examination of the results in the AD study, we have found that the  
30 subjects wrongly classified maybe the most critical ones: old control subjects  
31 classified as AD (false positives) and subjects with a very early or mild dementia  
32 classified as normal (false negatives), exactly the ones which are the target in  
33 these studies that try to perform early detection of AD. Post-mortem confir-  
34 mation data of AD diagnosed subjects could improve the results. Something  
35 similar may be happening in the MD1 study. Therefore we may conclude that  
36 additional information sources and improved classification strategies are needed  
37 to reach this additional accuracy increase that would cover the most difficult  
38 cases.  
39

40 Further work may be directed in the following lines:

- 41
- 42 • The consideration of features extracted on the basis of information ob-  
43 tained from other morphological measurement techniques, such as Deformation-  
44 based Morphometry and Tensor-based Morphometry.
- 45
- 46 • Use additional image modalities (PET, fMRI, DTI) and additional clinical  
47 data. Additional image modalities imply the mutual registration of vol-  
48 umes and the fusion of the diverse information sources. Additional clinical  
49 data may be used as covariates in the GLM resolution within the VBM  
50 analysis.
- 51
- 52 • Using new classification strategies, such as the uncertain classifiers, which  
53 may assign various grades to the data and provide new ways to evaluate  
54 the classifier response[47]. In the case of of pathologies with cognitive  
55 impairment, it would be more natural to try to rank the image data ac-  
56 cording to the neuropsychological scales than the binary decision that we  
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9 have been trying to implement in this paper, improving results in several  
10 ways. Also Lattice Computing approaches [28, 30, 26, 29, 27, 32]

- 11 • Future work may be addressed to the problem of three way discrimination  
12 AD vs. MD1 vs. controls. It needs an elaborated VBM using F test  
13 for the detection of clusters of voxels which can discriminate between the  
14 three classes, as well as multi-class classifiers, which in some cases requires  
15 some elaboration.  
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